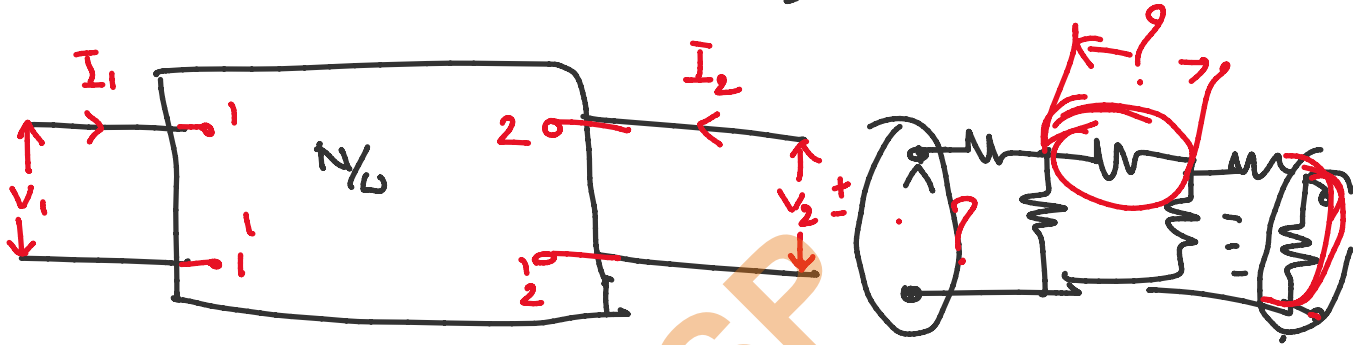


Two port network

(A collection of many elements to perform some meaningful work)



A pair of terminals thru' which the signal enters or leaves the n/o is called a port.

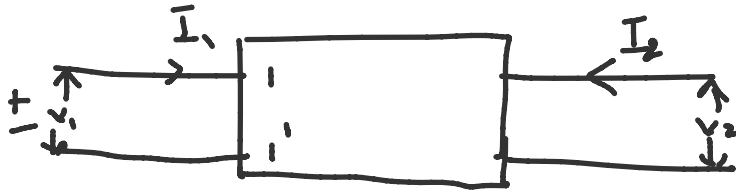


To be represented acc. to some convenience of us!

- ① Series - Impedance ✓
- ② Parallel - Admittance

(Two port ✓)

- ② Parallel - Admittance (Two port $\frac{1}{2}$ parameters)
- ③ Cascade - ABCD ✓
- ④ Amplifier - h-parameters



V_1, I_1, V_2, I_2
are my parameters
of interest

(2 parameters to be dependent & another 2 parameters to be independent)

Active port - Source

Passive port - No source

Two port $\frac{1}{2}$ parameters - All parameters are obtained conditionally

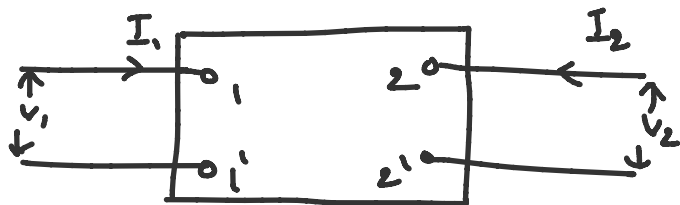
ex:- $\frac{V_1}{I_1} \Big|_{I_2=0}$ $\frac{V_1}{V_2} \Big|_{I_1=0}$

Not Generalized Rates \times Conditional Rates

Generalized - $\frac{1}{2}$ Functions

Z-Parameters (open circuit z parameters)

18 December 2020 09:45



$$V_1, I_1, V_2, I_2$$

Z-parameters

I_1, I_2 - Independent parameters

V_1, V_2 - Dependent parameters

$$V_1 = f(I_1, I_2)$$

$$V_2 = f(I_1, I_2)$$

$$V_1 = Z_{11}I_1 + Z_{12}I_2 \quad \text{--- (1)}$$

$$V_2 = Z_{21}I_1 + Z_{22}I_2 \quad \text{--- (2)}$$

Z_{12} → Port no; of the independent param

Port no; of the parameter to be calculated

$$Z_{11} = \left. \frac{V_1}{I_1} \right|_{I_2=0} \quad \text{--- Open ckt + input impedance}$$

- Driving point Open ckted impedance

$$Z_{21} = \left. \frac{V_2}{I_1} \right|_{I_2=0} \quad \text{--- Transfer Impedance at port 1 with port 2 o.c.}$$

- (Open ckt Transfer Impedance)

$$Z_{12} = \left. \frac{V_1}{I_2} \right|_{I_1=0} \quad \text{--- Transfer impedance at port 2 with port 1 o.c.}$$

$$Z_{22} = \left. \frac{V_2}{I_2} \right|_{I_1=0} \quad \text{--- Driving pt impedance at port 2 with port 1 o.c.}$$

$$Z_{22} = \frac{V_2}{I_2} \Big|_{I_1=0} \quad \text{--- Driving pt impedance at port 2} \\ \text{--- port 1 o.c.} \\ \text{(Open circuit w.r impedance)}$$

$$V_1 = Z_{11} I_1 + Z_{12} I_2$$

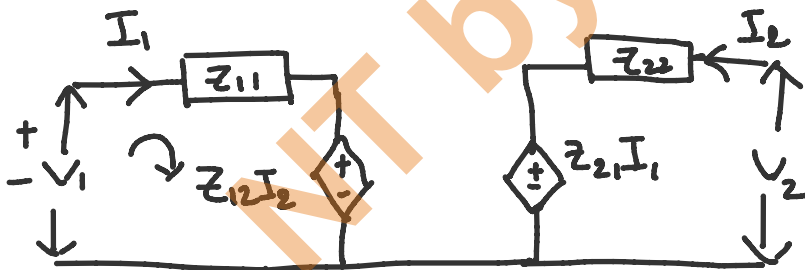
$$V_2 = Z_{21} I_1 + Z_{22} I_2$$

Impedance matrix

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix} \Rightarrow V = Z I \rightarrow \text{Circuit matrix}$$

↓
Voltage Matrix

$$\left. \begin{aligned} V_1 &= Z_{11} I_1 + Z_{12} I_2 \quad \text{--- (1)} \\ V_2 &= Z_{21} I_1 + Z_{22} I_2 \quad \text{--- (2)} \end{aligned} \right\} \text{Mesh eqns.}$$



Pictorial or circuit of the two port eqns

$$Z_{21} = Z_{12} \quad \text{--- Reciprocal } \frac{1}{\omega} \text{ or Bilateral } \frac{1}{\omega}$$

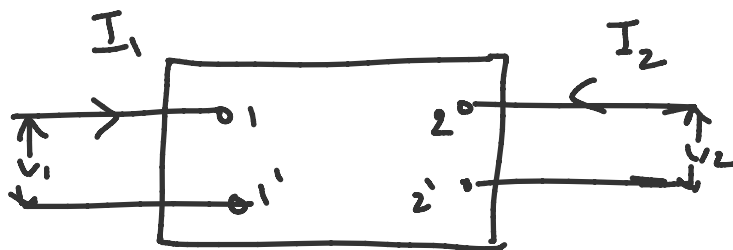
$$\frac{V_2}{I_1} \Big|_{I_2=0} = \frac{V_1}{I_2} \Big|_{I_1=0}$$

All parameters are in \$\Omega\$

NT by PSP

Y-Parameters (Short Circuited Y Parameters)

18 December 2020 10:01



I in terms of voltages.

I_1, I_2 - dependent
 V_1, V_2 - Independent.

$$I_1 = Y_{11} V_1 + Y_{12} V_2$$

$$I_2 = Y_{21} V_1 + Y_{22} V_2$$

$Y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0}$ - Driving pt admittance at port 1 with port 2 s.c.

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} Y_{11} & Y_{12} \\ Y_{21} & Y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

↳ Admittance

$Y_{21} = \frac{I_2}{V_1} \Big|_{V_2=0}$ - Transfer Admittance at port 1 with port 2 s.c.

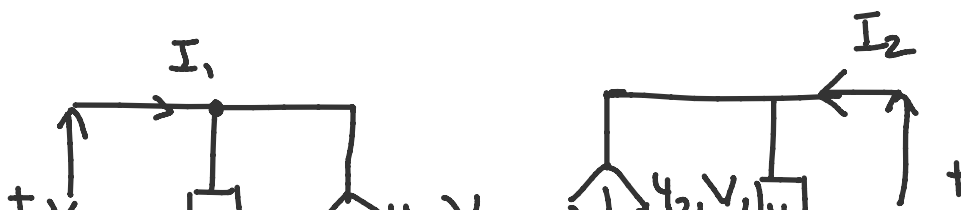
$Y_{12} = \frac{I_1}{V_2} \Big|_{V_1=0}$ - Trans. Admittance at port 2 with port 1 s.c.

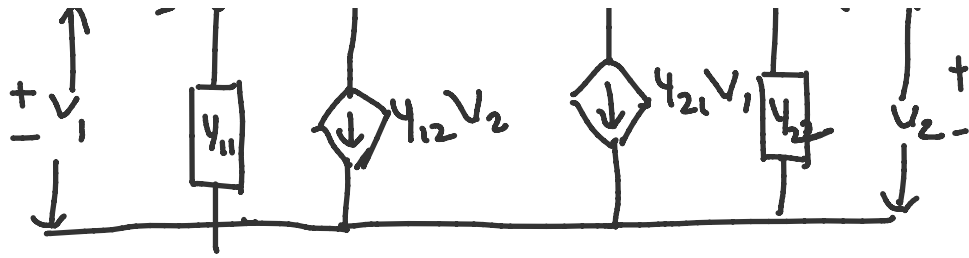
$Y_{22} = \frac{I_2}{V_2} \Big|_{V_1=0}$ - Driving pt Admittance at port 2 with port 1 s.c.

$$I_1 = Y_{11} V_1 + Y_{12} V_2$$

$$I_2 = Y_{21} V_1 + Y_{22} V_2$$

Dependent current sources.





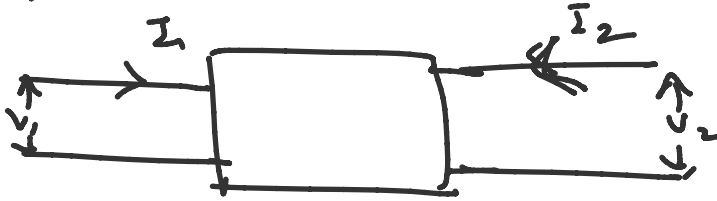
All parameter are is \underline{V}

NT by PSP

ABCD Parameters (Transmission Parameters)

18 December 2020 10:09

Input port is sep. in terms of $\%$ port parameters



V_2, I_2 are independent
 V_1, I_1 are dependent

$$V_1 = AV_2 + B(-I_2)$$

$$I_1 = CV_2 + D(-I_2)$$

To make the current going out of the $\%$ port as a - sign is attributed to I_2 incoming current

$$V_1 = AV_2 - BI_2$$

$$I_1 = CV_2 - DI_2$$

B & D

$$-I_2$$

Port 1

$$\begin{pmatrix} V_1 \\ I_1 \end{pmatrix} = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} V_2 \\ -I_2 \end{pmatrix}$$

Port 2

$$A = \left. \frac{V_1}{V_2} \right|_{I_2=0}$$

- Gain parameter
No units

$$C = \left. \frac{I_1}{V_2} \right|_{I_2=0}$$

Open ckt the $\%$ port
DC Admittance parameter

$$\frac{1}{C} = \left. \frac{V_2}{I_1} \right|_{I_2=0} = Z_{21}$$

$$\boxed{Z_{21} = \frac{1}{C}}$$

$$I_1, I_2 = 0$$

$$\boxed{Z_{21} = \frac{1}{C}}$$

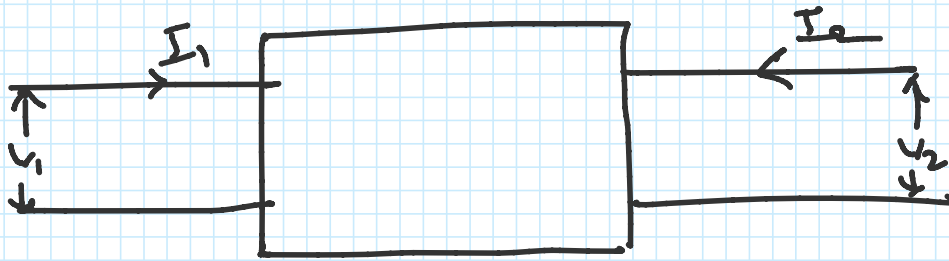
$$B = \left. \frac{V_1}{-I_2} \right|_{V_2=0} \Rightarrow -B = \left. \frac{V_1}{I_2} \right|_{V_2=0} = \frac{1}{Y_{21}} \text{ Impedance per unit port 2 S.C}$$

$$D = \left. \frac{I_1}{-I_2} \right|_{V_2=0} \Rightarrow -D = \left. \frac{I_1}{I_2} \right|_{V_2=0} \text{ Current gain no units}$$

NT by PSP

Inverse Transmission Parameters

18 December 2020 10:19



% per parameters are exp. in terms of $\frac{I}{V}$
per parameters

$$V_2 = A'V_1 - B'I_1$$

$$I_2 = C'V_1 - D'I_1$$

$$-B' = \left. \frac{V_2}{I_1} \right|_{V_1=0}$$

$$-D' = \left. \frac{I_2}{I_1} \right|_{V_1=0}$$

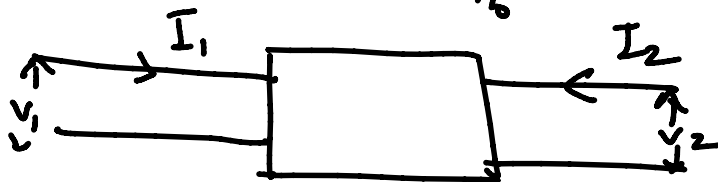
$$A' = \left. \frac{V_2}{V_1} \right|_{I_1=0}$$

$$C' = \left. \frac{I_2}{V_1} \right|_{I_1=0}$$

NT by PSP

hybrid parameters - used in analysis of Amplifiers.

→ A_v, A_i, R_i, R_o → h-parameters exactly.



V_1, I_2 - Dependent Parameters

I_1, V_2 - Independent

$$V_1 = h_{11} I_1 + h_{12} V_2 \quad \text{--- (1)}$$

$$I_2 = h_{21} I_1 + h_{22} V_2 \quad \text{--- (2)}$$

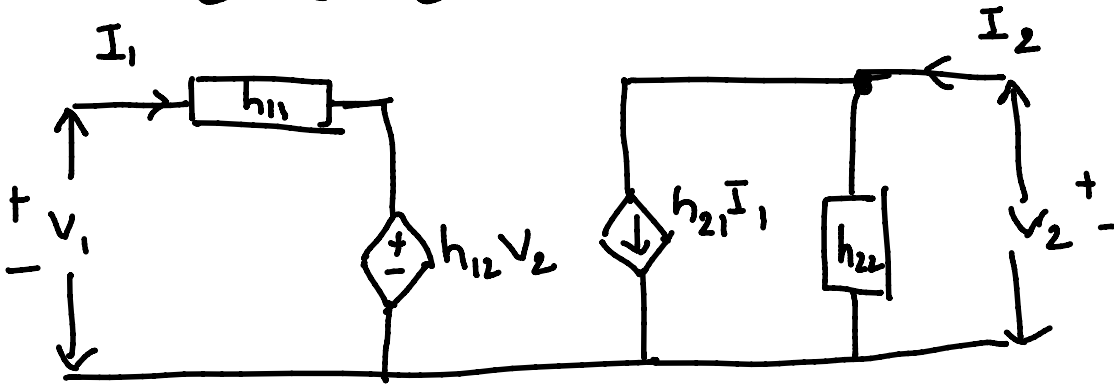
$$h_i = h_{11} = \frac{V_1}{I_1} \Big|_{V_2=0} \quad \text{Port 2 S.C. - Input impedance at Port-1 } (\Omega)$$

$$h_r = h_{12} = \frac{V_1}{V_2} \Big|_{I_1=0} \quad \text{Port 1 O.C. - Reverse Voltage Gain (No units)}$$

$$h_f = h_{21} = \frac{I_2}{I_1} \Big|_{V_2=0} \quad \text{Port 2 S.C. - Forward Current gain (No units)}$$

$$h_o = h_{22} = \frac{I_2}{V_2} \Big|_{I_1=0} \quad \text{Port 1 O.C. - } \Omega_p \text{ Admittance } (\Omega^{-1})$$

$$\begin{pmatrix} V_1 \\ I_2 \end{pmatrix} = \begin{pmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{pmatrix} \begin{pmatrix} I_1 \\ V_2 \end{pmatrix}$$



NT by PSP

Inverse hybrid parameters

19 December 2020 10:44

I_1, V_2 are expressed in terms of V_1, I_2

$$I_1 = g_{11}V_1 + g_{12}I_2$$

$$V_2 = g_{21}V_1 + g_{22}I_2$$

$$g_{11} = \left. \frac{I_1}{V_1} \right|_{I_2=0} \quad \text{o.c. } I/P \quad \text{Admittance}$$

$$g_{12} = \left. \frac{I_1}{I_2} \right|_{V_1=0} \quad I/P \text{ shorted, Reverse current gain}$$

$$g_{21} = \left. \frac{V_2}{V_1} \right|_{I_2=0} \quad \text{o/p o.c., f. Voltage Gain}$$

$$g_{22} = \left. \frac{V_2}{I_2} \right|_{V_1=0} \quad - \quad I/P \text{ shorted, o/p impedance}$$

Represent one parameter in terms of the other parameters

19 December 2020 10:47

Rep of Y is term Z .

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$$V = Z I \quad - \textcircled{1}$$

from eq $\textcircled{1}$

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

$$I = \frac{V}{Z}$$

$$I = V Z^{-1} - \textcircled{1}'$$

$$I = Y V - \textcircled{2} \quad \text{From eq } \textcircled{1}' \text{ \& } \textcircled{2}$$

$$Y = Z^{-1}$$

$$Z = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix}$$

$$Y = Z^{-1} = \frac{1}{\Delta Z} \begin{bmatrix} z_{22} & -z_{12} \\ -z_{21} & z_{11} \end{bmatrix}$$

$$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} = \begin{bmatrix} \frac{z_{22}}{\Delta Z} & -\frac{z_{12}}{\Delta Z} \\ -\frac{z_{21}}{\Delta Z} & \frac{z_{11}}{\Delta Z} \end{bmatrix}$$

$$V = Z I \quad I = Y V$$

Z parameter is term of Y parameter

Z parameters is term of Y parameters

$$V = \frac{I}{Y} = I Y^{-1}$$

$$Z = Y^{-1} \Rightarrow \begin{pmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{pmatrix} = \begin{pmatrix} Y_{22} & -Y_{12} \\ -Y_{21} & Y_{11} \end{pmatrix} / \Delta Y$$

$$\left(\begin{array}{ll} Z_{11} = Y_{22} / \Delta Y & Z_{12} = -Y_{12} / \Delta Y \\ Z_{21} = -Y_{21} / \Delta Y & Z_{22} = +Y_{11} / \Delta Y \end{array} \right)$$

$$Z = Y^{-1} \text{ or } Y = Z^{-1}$$

$$* Z_{12} = Z_{21} \Rightarrow -\frac{Y_{12}}{\Delta Y} = -\frac{Y_{21}}{\Delta Y} \Rightarrow \boxed{Y_{12} = Y_{21}}$$

Rep. of h-parameters is term of Z-parameters

$$V_1 = Z_{11} I_1 + Z_{12} I_2 \text{ --- (1)}$$

$$V_1 = h_{11} I_1 + h_{12} V_2 \text{ --- (3)}$$

$$V_2 = Z_{21} I_1 + Z_{22} I_2 \text{ --- (2)}$$

$$I_2 = h_{21} I_1 + h_{22} V_2 \text{ --- (4)}$$

$$h_{11} = \left. \frac{V_1}{I_1} \right|_{\underline{\underline{V_2=0}}}$$

in eq (2) if $V_2 = 0$

$$0 = Z_{21} I_1 + Z_{22} I_2$$

Sub (5) in (1)

$$Z_{21} I_1 = -Z_{22} I_2$$

Sub ⑤ is ①

$$z_{21} I_1 = -z_{22} I_2$$

$$V_1 = z_{11} I_1 - \frac{z_{12} z_{21} I_1}{z_{22}} =$$

$$I_2 = -\frac{z_{21}}{z_{22}} I_1 \text{---} ⑤$$

$$V_1 = \frac{(z_{11} z_{22} - z_{12} z_{21}) I_1}{z_{22}} \Rightarrow h_{11} = \frac{V_1}{I_1} \Big|_{V_2=0} = \frac{\Delta z}{z_{22}} \text{---} ⑥$$

$$h_{21} = \frac{I_2}{I_1} \Big|_{V_2=0} = -\frac{z_{21}}{z_{22}} \text{---} ⑦$$

Make $I_1=0$ in eq ① & ②

$$V_1 = z_{12} I_2$$

$$(V_2 = z_{22} I_2)$$

$$h_{12} = \frac{V_1}{V_2} \Big|_{I_1=0} = \frac{z_{12} I_2}{z_{22} I_2} = \frac{z_{12}}{z_{22}}$$

$$h_{12} = \frac{z_{12}}{z_{22}} \text{---} ⑧$$

$$h_{22} = \frac{I_2}{V_2} \Big|_{I_1=0} = \frac{1}{z_{22}} \text{---} ⑨$$

$$\begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} = \begin{bmatrix} \frac{\Delta z}{z_{22}} & \frac{z_{12}}{z_{22}} \\ -\frac{z_{21}}{z_{22}} & \frac{1}{z_{22}} \end{bmatrix}$$

ABCD is terms of z

$$V_1 = z_{11}I_1 + z_{12}I_2 \quad \text{--- (1)} \quad V_1 = AV_2 - BI_2 \quad \text{--- (3)}$$

$$V_2 = z_{21}I_1 + z_{22}I_2 \quad \text{--- (2)} \quad I_1 = CV_2 - DI_2 \quad \text{--- (4)}$$

$$A = \left. \frac{V_1}{V_2} \right|_{I_2=0} = \frac{z_{11}I_1}{z_{21}I_1} = \frac{z_{11}}{z_{21}} \quad \text{--- (5)}$$

$$V_1 = z_{11}I_1$$

Making $I_2 = 0$ is eq (1) & (2)

$$V_2 = z_{21}I_1$$

$$C = \left. \frac{I_1}{V_2} \right|_{I_2=0} = \frac{1}{z_{21}} \quad \text{--- (6)}$$

Making $V_2 = 0$ is eq (2)

$$0 = z_{21}I_1 + z_{22}I_2$$

$$I_2 = -\frac{z_{21}I_1}{z_{22}} \quad \text{--- (7)}$$

Sub (7) is eq (1)

$$V_1 = z_{11} \left(-I_2 \frac{z_{22}}{z_{21}} \right) + z_{12}I_2$$

$$I_1 = -I_2 \frac{z_{22}}{z_{21}} \quad \text{--- (7)}$$

$$V_1 = \left(\frac{-z_{11}z_{22} + z_{12}z_{21}}{z_{21}} \right) I_2$$

--- (8)

$$B = -\frac{V_1}{I_2} = \frac{(z_{12}z_{21} + z_{11}z_{22})}{z_{21}}$$

$$= \frac{z_{11}z_{22} - z_{21}z_{12}}{z_{21}}$$

$$D = -\frac{I_1}{I_2} = \frac{z_{22}}{z_{21}}$$

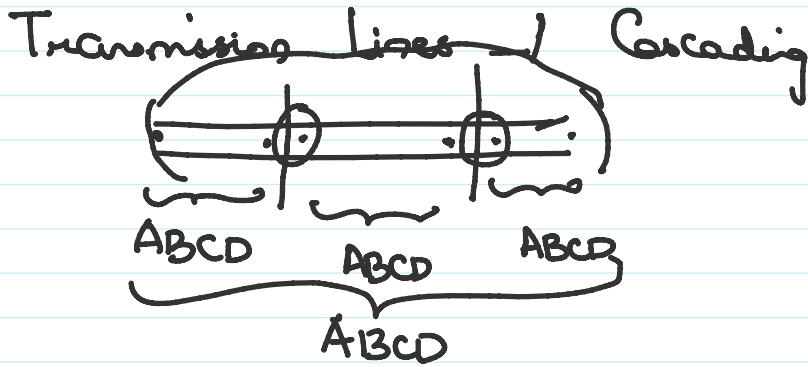
$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{pmatrix} \frac{z_{11}}{z_{21}} & \frac{z_{11}z_{22} - z_{12}z_{21}}{z_{21}} \\ \frac{1}{z_{21}} & \frac{z_{22}}{z_{21}} \end{pmatrix}$$

NT by PSP

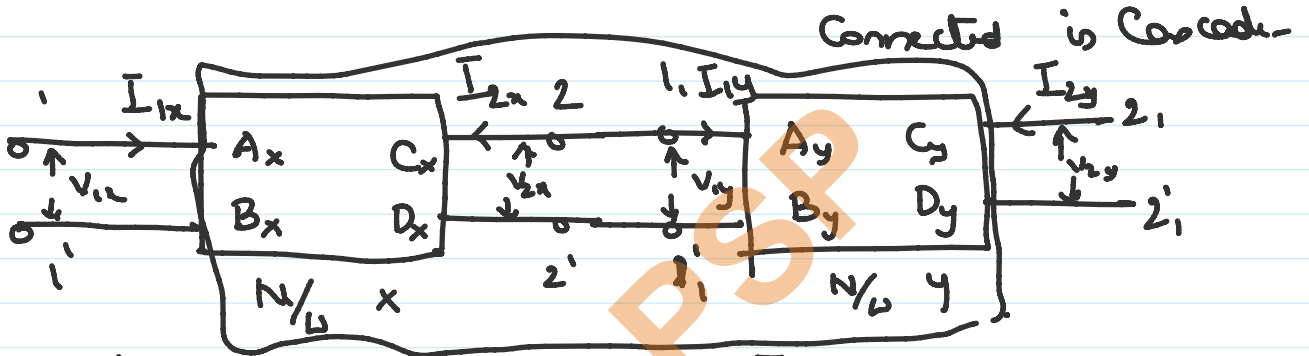
Cascade Connection, Series Connection, Parallel Connection

19 December 2020 11:09

Cascade Connection:



To find the Resultant ABCD parameters of all the Transmission lines



V_{2y} & I_{1x} related, I_{2y} & I_{1x} related.

For $N/w x$

$$\begin{bmatrix} V_{1x} \\ I_{1x} \end{bmatrix} = \begin{bmatrix} A_x & B_x \\ C_x & D_x \end{bmatrix} \begin{bmatrix} V_{2x} \\ -I_{2x} \end{bmatrix} \quad \text{--- (1)}$$

For $N/w y$

$$\begin{bmatrix} V_{1y} \\ I_{1y} \end{bmatrix} = \begin{bmatrix} A_y & B_y \\ C_y & D_y \end{bmatrix} \begin{bmatrix} V_{2y} \\ -I_{2y} \end{bmatrix} \quad \text{--- (2)}$$

According to connection

$$\begin{bmatrix} V_{2x} \\ -I_{2x} \end{bmatrix} = \begin{bmatrix} V_{1y} \\ I_{1y} \end{bmatrix} \quad \text{--- (3)}$$

Writing (2) again

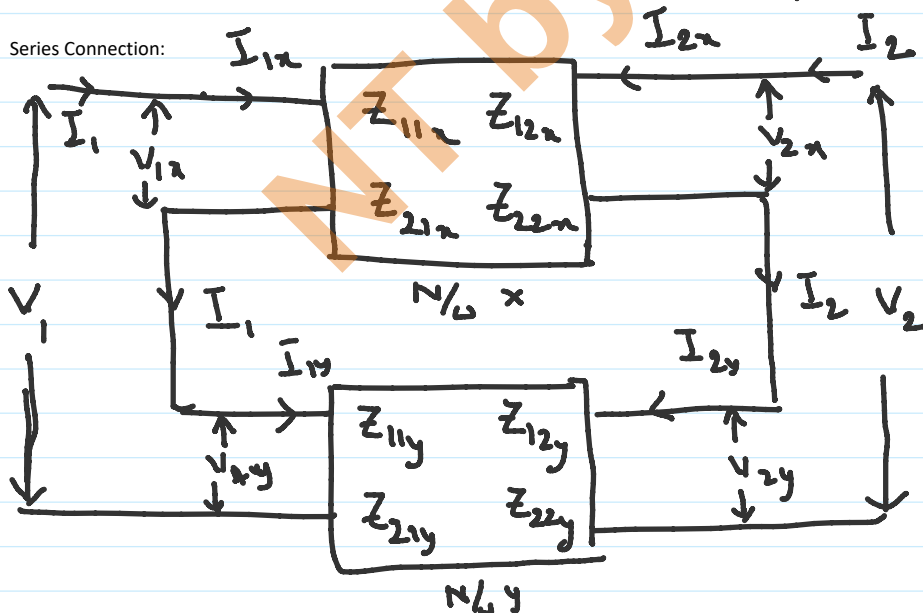
Write (2) again

$$\begin{bmatrix} V_{2x} \\ -I_{2x} \end{bmatrix} = \begin{bmatrix} V_{1y} \\ I_{1y} \end{bmatrix} = \begin{bmatrix} A_y & B_y \\ C_y & D_y \end{bmatrix} \begin{bmatrix} V_{2y} \\ -I_{2y} \end{bmatrix} \quad (4)$$

Combining (1) & (4)

$$\begin{bmatrix} V_{1x} \\ I_{1x} \end{bmatrix} = \begin{bmatrix} A_x & B_x \\ C_x & D_x \end{bmatrix} \begin{bmatrix} A_y & B_y \\ C_y & D_y \end{bmatrix} \begin{bmatrix} V_{2y} \\ -I_{2y} \end{bmatrix} \quad (5)$$

The Resultant ABCD parameters of the Cascaded N 's are a Matrix Multiplication of the individual N 's ABCD parameters.



$$I_1 = I_{1x} = I_{1y} \quad (1) \quad V_1 = V_{1x} + V_{1y} \quad (2)$$

$$I_2 = I_{2x} = I_{2y} \quad (3) \quad V_2 = V_{2x} + V_{2y} \quad (4)$$

For N/x

$$V_{1x} = Z_{11x} I_{1x} + Z_{12x} I_{2x} \quad (5)$$

for N/L \wedge

$$V_{1x} = Z_{11x} I_{1x} + Z_{12x} I_{2x} \quad \text{--- (5)}$$

$$V_{2x} = Z_{21x} I_{1x} + Z_{22x} I_{2x} \quad \text{--- (6)}$$

For N/L y

$$V_{1y} = Z_{11y} I_{1y} + Z_{12y} I_{2y} \quad \text{--- (7)}$$

$$V_{2y} = Z_{21y} I_{1y} + Z_{22y} I_{2y} \quad \text{--- (8)}$$

For the Combined Series N/L ($V_1, V_2 \rightarrow I_1, I_2$)

from eq (3), $V_1 = V_{1x} + V_{1y}$ (sub 5 & 7 in 3)

$$V_1 = Z_{11x} I_{1x} + Z_{12x} I_{2x} + Z_{11y} I_{1y} + Z_{12y} I_{2y}$$

(from (1) & (2) eqn we know $I_1 = I_{1x} = I_{1y}$,
 $I_2 = I_{2x} = I_{2y}$)

$$V_1 = (Z_{11x} + Z_{11y}) I_1 + (Z_{12x} + Z_{12y}) I_2 \quad \text{--- (9)}$$

Similarly from (4) $V_2 = V_{2x} + V_{2y}$ (sub 6 & 8 in 4)

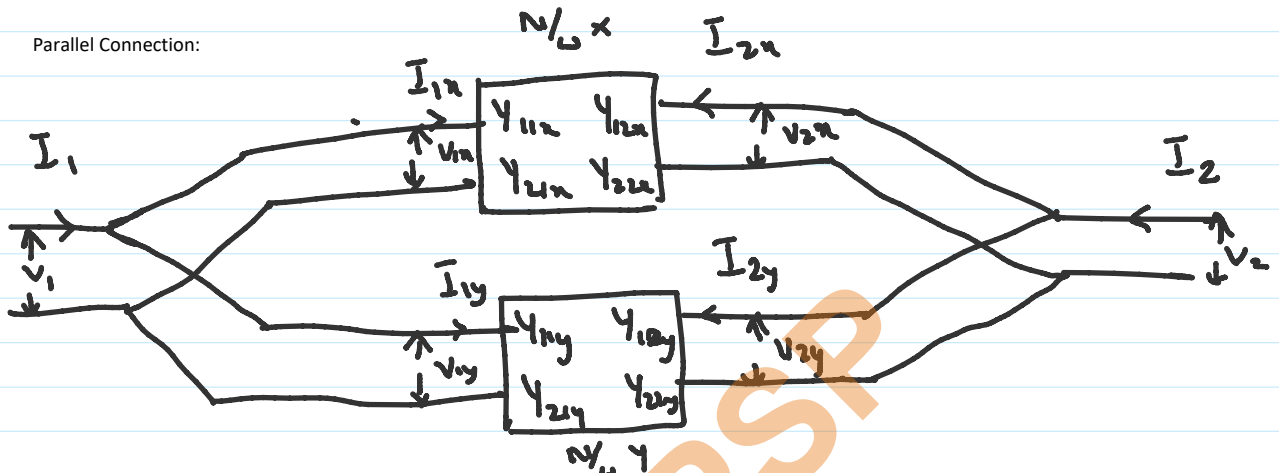
$$V_2 = Z_{21x} I_{1x} + Z_{22x} I_{2x} + Z_{21y} I_{1y} + Z_{22y} I_{2y}$$

$$V_2 = (Z_{21x} + Z_{21y}) I_1 + (Z_{22x} + Z_{22y}) I_2 \quad \text{--- (10)}$$

$$\begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} Z_{11x} + Z_{11y} & Z_{12x} + Z_{12y} \\ Z_{21x} + Z_{21y} & Z_{22x} + Z_{22y} \end{pmatrix} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix}$$

$\left[\begin{matrix} V_2 \end{matrix} \right]$ $\left[\begin{matrix} -212 + 121y \end{matrix} \right]$ --- $-JL$ ✓
 So 2 n/w Connected in series, have their z-parameters are a summation of the z-parameters of individual n/w .

Parallel Connection:



$$V_1 = V_{1x} = V_{1y} \quad \text{--- (1)}$$

$$I_1 = I_{1x} + I_{1y} \quad \text{--- (3)}$$

$$V_2 = V_{2x} = V_{2y} \quad \text{--- (2)}$$

$$I_2 = I_{2x} + I_{2y} \quad \text{--- (4)}$$

For $n/w x$

$$I_{1x} = Y_{11x} V_{1x} + Y_{12x} V_{2x} \quad \text{--- (5)}$$

$$I_{2x} = Y_{21x} V_{1x} + Y_{22x} V_{2x} \quad \text{--- (6)}$$

For $n/w y$

$$I_{1y} = Y_{11y} V_{1y} + Y_{12y} V_{2y} \quad \text{--- (7)}$$

$$I_{2y} = Y_{21y} V_{1y} + Y_{22y} V_{2y} \quad \text{--- (8)}$$

from eq (3) $I_1 = I_{1x} + I_{1y}$ (5 & 6 is 3)

$$I_1 = Y_{11x} V_{1x} + Y_{12x} V_{2x} + Y_{11y} V_{1y} + Y_{12y} V_{2y}$$

(from $V_{1x} = V_{1y} = V_1$)

$$I_1 = (Y_{11x} + Y_{11y}) V_1 + (Y_{12x} + Y_{12y}) V_2 \quad \text{--- (9)}$$

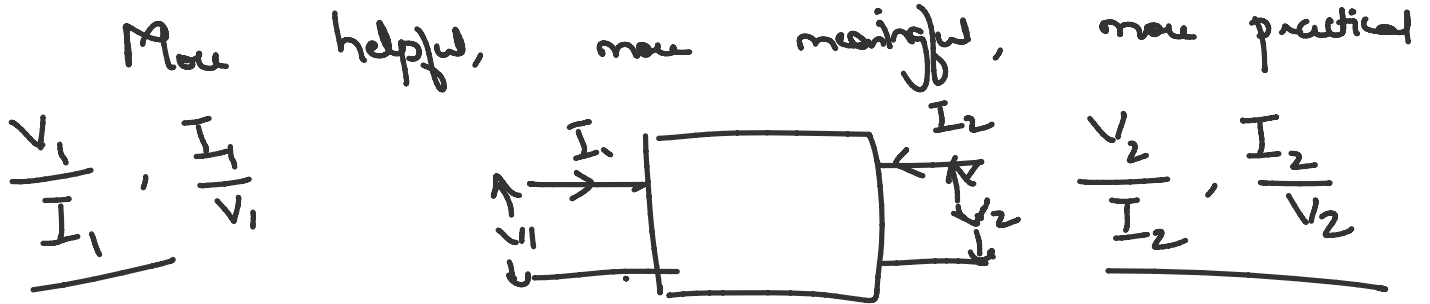
$$I_1 = (Y_{11x} + Y_{11y})V_1 + (Y_{12x} + Y_{12y})V_2 - \textcircled{9}$$

$$I_2 = Y_{21x}V_{1x} + Y_{22x}V_{2x} + Y_{21y}V_{1y} + Y_{22y}V_{2y}$$

$$I_2 = (Y_{21x} + Y_{21y})V_1 + (Y_{22x} + Y_{22y})V_2 - \textcircled{10}$$

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} Y_{11x} + Y_{11y} & Y_{12x} + Y_{12y} \\ Y_{21x} + Y_{21y} & Y_{22x} + Y_{22y} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

Y parameters of Parallel Connectors are summates of Y-parameters of Individual $\frac{1}{L}$ -



$$G_{21} = \frac{V_2}{V_1}$$

Ratio of parameters

Driving Point Function of same port is called DP.

Transfer Function - Ratio of parameter b/w voltage diff parts this it is transfer

$\frac{I_1}{I_2}, \frac{I_2}{I_1}, \frac{V_1}{V_2}, \frac{V_2}{V_1}, \frac{I_1}{V_2}, \frac{V_2}{I_1}, \frac{I_2}{V_1}, \frac{V_1}{I_2}$

Current Ratio, Trans Imp or Admittance

$$Z_{21} \quad Y_{21}$$

$$Z_{21} \quad Y_{21}$$

$$Z_{21} \quad Y_{21}$$

$$Z_{21}(s) \rightarrow$$

$$Y_{21}(s) -$$

N/D, Functⁿ



Zer

Pole

N/D

$$s = \sigma + j\omega$$

$$G_{21}(s) =$$

$$\frac{s^2 + 3s + 2}{s^2 + 5s + 6}$$

$$\frac{(s+2)(s+1)}{(s+2)(s+3)} = \frac{s}{s+3} = \frac{\infty}{\infty}$$

$s = \sigma + j\omega$

$$G_{21}(s) = \frac{1}{s^2 + 5s + 6} = \frac{1}{(s+2)(s+3)}$$


$s = -2, s = -3 \rightarrow$ * Roots of $D_r \rightarrow$ Pole * $\frac{(s+1)}{(s+3)}$
 $s = -2, s = -1 \rightarrow$ * Roots of $N_r \rightarrow$ Zeros * $\frac{(s+1)}{(s+3)}$

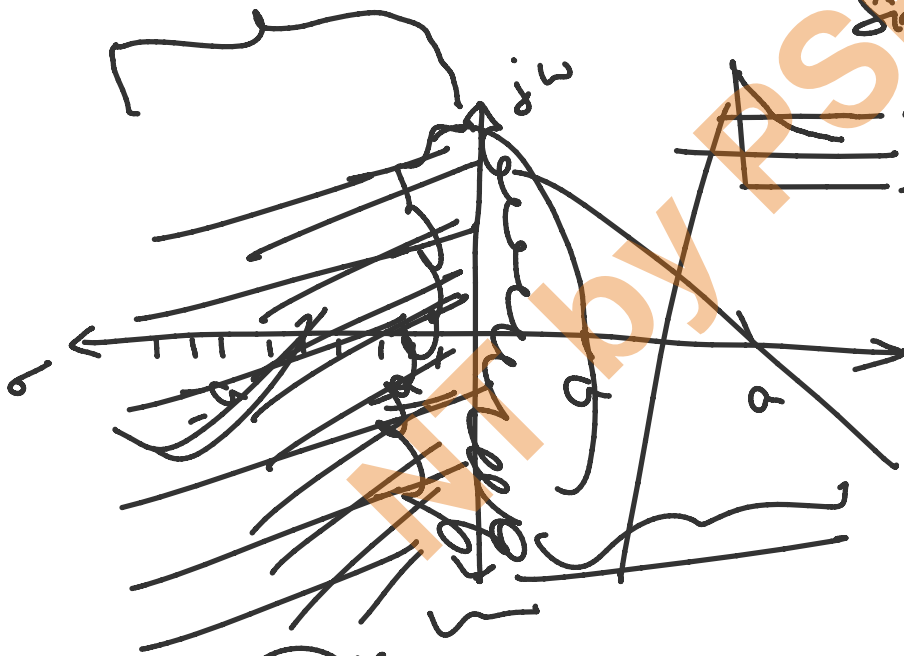
$$G_{21}(s) = \frac{(s - (-2))(s - (-1))}{(s - (-2))(s - (-3))}$$

' ∞ ' \rightarrow Indeterminate

$$K \frac{(s+1)(s+1)}{(s+1)(s+1)}$$

$$(s+1)^2 = s^2 + 1$$

$\sin t$ 



Real part is -ve

$$\frac{1}{s+a} \Rightarrow \frac{e^{-st}}{s - (-a)} \Rightarrow \boxed{e^{-at}}$$


$$\frac{1}{s-a} = \frac{1}{s-(a)} = e^{at}$$

$$(s^2 + a^2) \quad s = \pm ja$$

$$(s + ja)(s + ja)$$

sin or cos

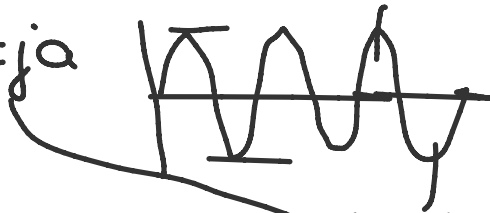


sin or Cos 

$s^2 + s + 1$
RLC

$Ls + \frac{1}{C} \Rightarrow \frac{Ls^2 + 1}{Cs}$

$\sqrt{s^2 + a^2} \Rightarrow s = \pm ja$
 sin / Cos



$(s + ja)(s + ja_1)$
~~X~~

$as^2 + bs + c \rightarrow$ RLC

$Ls + \frac{1}{Cs} \Rightarrow \frac{Ls^2 + 1}{Cs}$

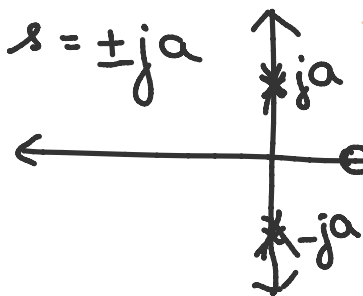
$s^2 = -1 \Rightarrow s = \pm j\sqrt{1/LC}$

$\frac{1}{(s^2 + a^2)^2} \Rightarrow$

$\frac{1}{s^2} \Rightarrow t$
 $t \sin at$ or $t \cos at$

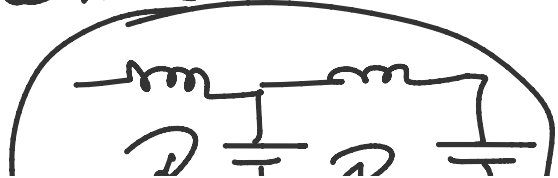
max

$\phi_p = \dots$



$\frac{1}{2s^4 + s^3 + 3s^2 + 2s + 3}$
RLC

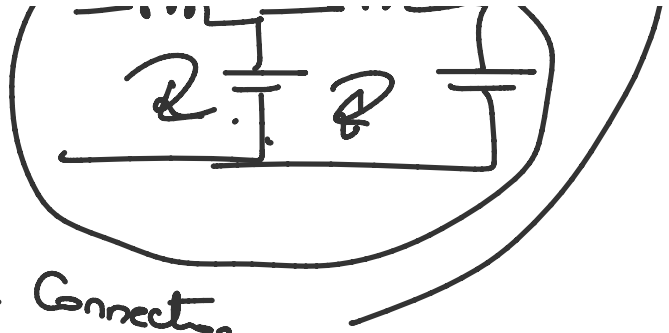
$s \frac{1}{(s^4 + s^2 + 1)} = \frac{1}{(s^5 + s^3 + s)}$



RLC

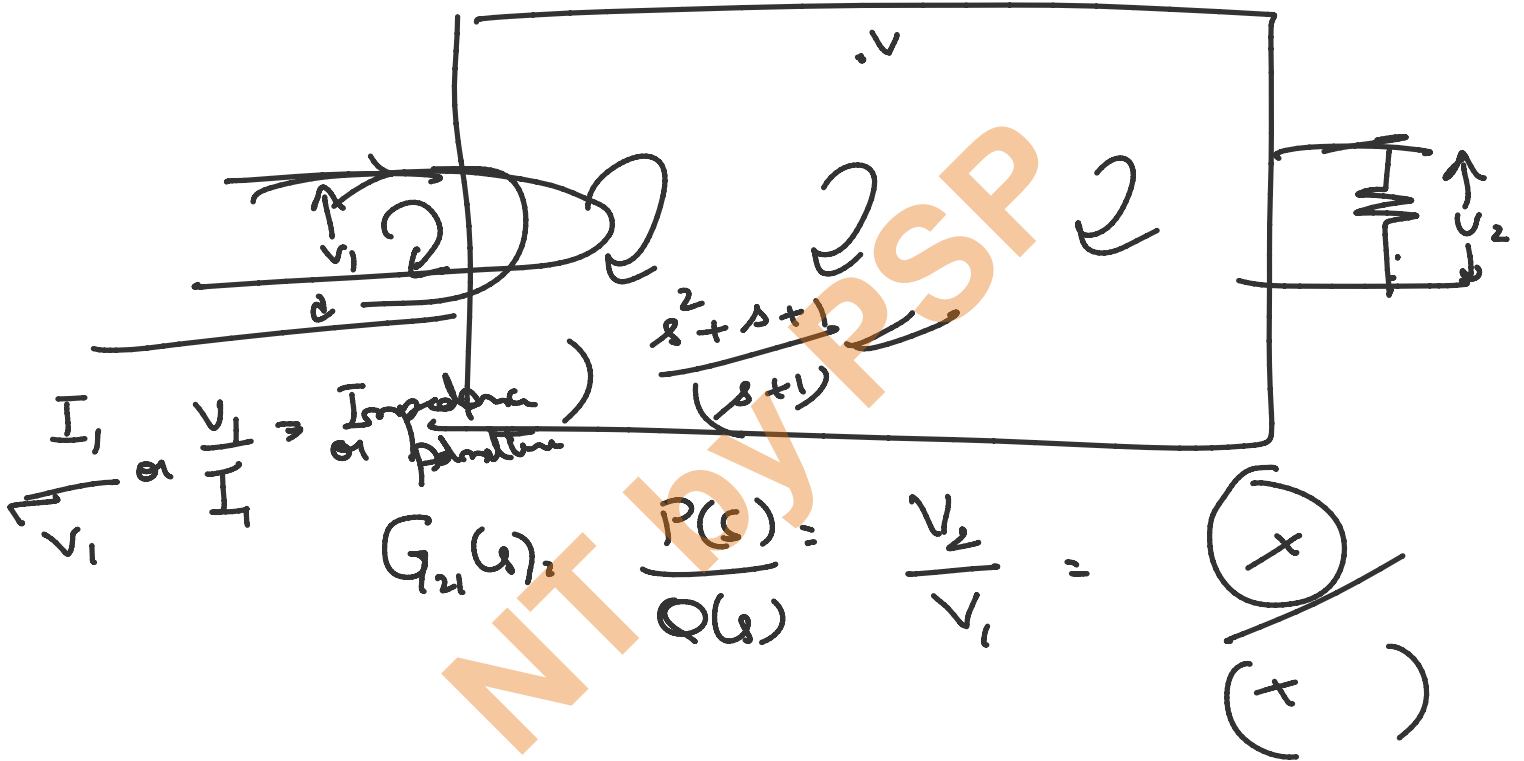
$$\frac{1}{s^4 + s^2 + 1} \checkmark$$

→ LC Connect

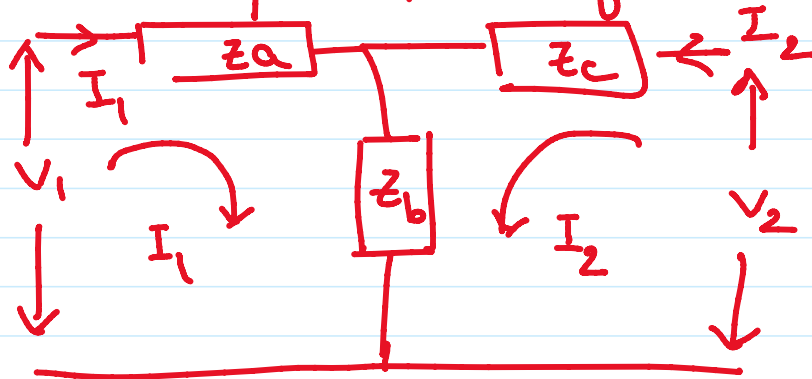


$$\frac{1}{s^4 + 0s^3 + s^2 + s + 1} \times$$

→ Cannot form a (valid γ_L)



① Find the Z -parameters for the ckt gives below



$$V_1 = Z_a I_1 + Z_b (I_1 + I_2)$$

$$V_1 = (Z_a + Z_b) I_1 + Z_b I_2 \quad \text{--- (1)}$$

$$V_2 = Z_c I_2 + Z_b (I_1 + I_2)$$

$$V_2 = Z_b I_1 + (Z_c + Z_b) I_2 \quad \text{--- (2)}$$

$$\begin{pmatrix} V_1 = (Z_a + Z_b) I_1 + Z_b I_2 \\ V_2 = Z_b I_1 + (Z_c + Z_b) I_2 \end{pmatrix}$$

$$Z_{11} = Z_a + Z_b$$

$$Z_{21} = Z_b$$

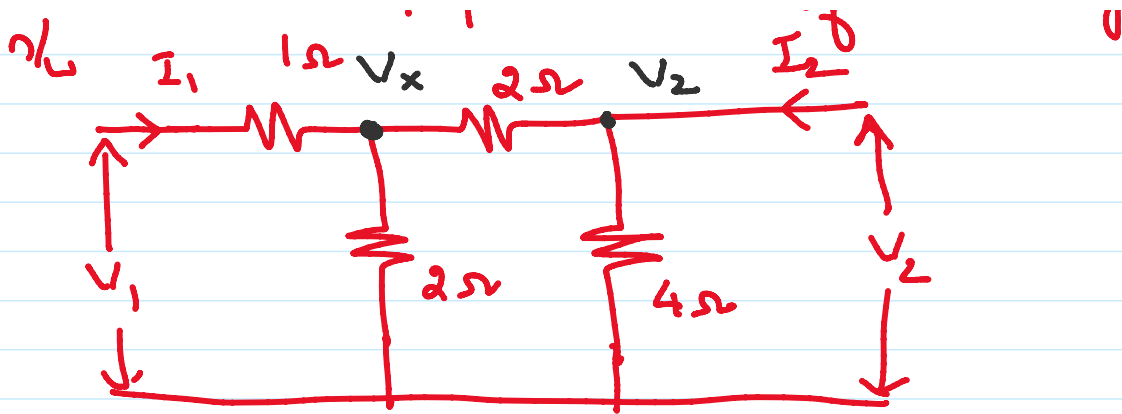
$$Z_{12} = Z_b$$

$$Z_{22} = (Z_c + Z_b)$$

$$\boxed{Z_{12} = Z_{21}}$$

Reciprocal n/w.

② Find the Y -parameters of the given n/w
 $\frac{I_1}{1\Omega} \quad \frac{I_2}{2\Omega}$ $\frac{V_1}{1\Omega} \quad \frac{V_2}{2\Omega}$



$$I_1 = \frac{V_1 - V_x}{1} \quad \text{--- (1)}$$

At node V_x $\left[\frac{V_x - V_1}{1} + \frac{V_x}{2} + \frac{V_x - V_2}{2} = 0 \right] \quad \text{--- (2)}$

At node V_2 $\frac{V_2 - V_x}{2} + \frac{V_2}{4} = I_2 \quad \text{--- (3)}$

Rearranging eq (2) such that V_x is expressed in terms of V_1 & V_2

$$V_x - V_1 + 0.5V_x + 0.5V_x - 0.5V_2 = 0$$

$$2V_x = V_1 + 0.5V_2$$

$$\Rightarrow V_x = \frac{V_1}{2} + \frac{0.5V_2}{2}$$

$$V_x = 0.5V_1 + 0.25V_2 \quad \text{--- (4)}$$

Sub (4) in (1) & (3)

eq (1) $I_1 = \frac{V_1 - V_x}{1} \Rightarrow I_1 = \frac{V_1 - (0.5V_1 + 0.25V_2)}{1}$

$$I_1 = 0.5V_1 - 0.25V_2 \quad \text{--- (5)}$$

$$\begin{aligned} \text{Q 3) } I_2 &= \frac{V_2}{4} + \frac{V_2 - V_x}{2} \\ &= \frac{V_2}{4} + \frac{V_2 - (0.5V_1 + 0.25V_2)}{2} \end{aligned}$$

$$= 0.25V_2 + 0.5V_2 - 0.25V_1 - 0.125V_2$$

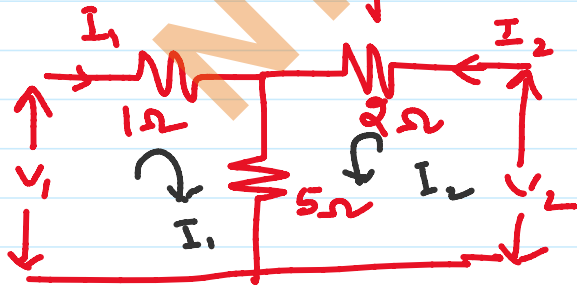
$$I_2 = -0.25V_1 + 0.625V_2 \quad \text{--- (6)}$$

$$I_1 = 0.5V_1 - 0.25V_2$$

$$I_2 = -0.25V_1 + 0.625V_2$$

$$Y_{11} = 0.5 \text{ } \Omega^{-1}, \quad Y_{12} = -0.25 \text{ } \Omega^{-1}, \quad Y_{21} = -0.25 \text{ } \Omega^{-1}, \quad Y_{22} = 0.625 \text{ } \Omega^{-1}$$

③ Find the ABCD parameters for the given CKI-



$$V_1 = 1 \times I_1 + 5(I_1 + I_2) \Rightarrow$$

$$V_2 = 2I_2 + 5(I_1 + I_2)$$

$$V_1 = 6I_1 + 5I_2 \quad \text{--- (1)}$$

$$V_2 = 5I_1 + 7I_2 \quad \text{--- (2)}$$

Making $I_2 = 0$
in eq (1) & (2)

$$V_1 = 6I_1$$

$$V_2 = 5I_1$$

$$\left. \frac{V_1}{V_2} \right|_{I_2=0} = \frac{6I_1}{5I_1} = A \quad \left| \quad I_2=0 \right.$$

$$A = \frac{6}{5} \quad \text{--- (3)}$$

$$V_2 = 5I_1 + 7I_2 \quad \text{--- (2)}$$

$$A = \frac{6}{5} \quad \text{--- (3)}$$

$$V_1 = AV_2 - BI_2$$

$$I_1 = CV_2 - DI_2$$

$$C = \left. \frac{I_1}{V_2} \right|_{I_2=0} = \frac{1}{5} \quad \text{--- (4)}$$

Making $V_2 = 0$ in eq (2)

$$5I_1 = -7I_2 \Rightarrow \frac{I_1}{I_2} = -\frac{7}{5}$$

$$D = \left. -\frac{I_1}{I_2} \right|_{V_2=0} = \frac{7}{5} \quad \text{--- (5)}$$

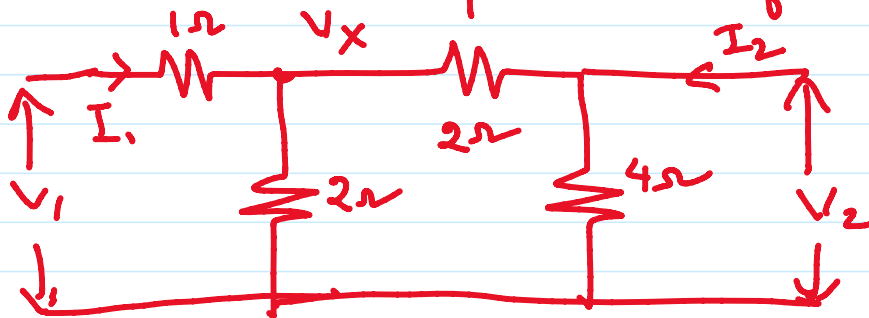
Sub $5I_1 = -7I_2$ in eq (1), $B = \left. -\frac{V_1}{I_2} \right|_{V_2=0}$

$$V_1 = 6 \cdot \left(-\frac{7}{5}\right) I_2 + 5I_2$$

$$V_1 = \left(\frac{-42 + 25}{5}\right) I_2 = -\frac{17}{5} I_2$$

$$B = +\frac{17}{5} \quad \text{--- (6)}$$

④ Find the h-parameters of the π .



$$I_1 = \frac{V_1 - V_x}{1} \quad \text{--- (1)}$$

$$\frac{V_x - V_1}{1} + \frac{V_x}{2} + \frac{V_x - V_2}{2} = 0 \quad \text{--- (2)}$$

$$\frac{V_2}{4} + \frac{V_2 - V_x}{2} = I_2 \quad \text{--- (3)}$$

eliminate
 V_x

$$I_1 = 0.5V_1 - 0.25V_2 \quad \text{--- (4)}$$

$$(I_2 = -0.25V_1 + 0.625V_2 \quad \text{--- (5)})$$

$$V_1 = h_{11}I_1 + h_{12}V_2$$

$$I_2 = h_{21}I_1 + h_{22}V_2$$

Making $V_2 = 0$ in (4) & (5)

$$I_1 = 0.5V_1$$

$$I_2 = -0.25V_1$$

$$h_{21} = \left. \frac{I_2}{I_1} \right|_{V_2=0} = \frac{-0.25V_1}{0.5V_1} = \underline{\underline{-0.5}}$$

$$h_{11} = \left. \frac{V_1}{I_1} \right|_{V_2=0} = \frac{2I_1}{I_1} = \underline{\underline{2\Omega}}$$

Making $I_1 = 0$ in eq (4)

$$0 = 0.5V_1 - 0.25V_2$$

$$0.5V_1 = 0.25V_2 \Rightarrow$$

$$\boxed{V_1 = \frac{V_2}{2}}$$

$$h_{12} = \frac{V_1}{V_2} \Big|_{I_1=0} = \frac{1}{2} = 0.5$$

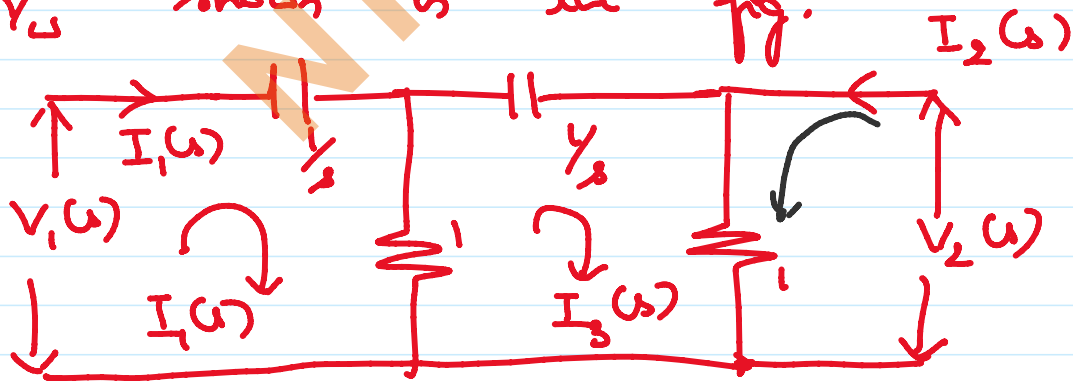
$$h_{22} = \frac{I_2}{V_2} \Big|_{I_1=0} = 0.5 \text{ } \Omega$$

$$I_2 = -0.25V_1 + 0.625V_2$$

$$I_2 = -0.25 \times \frac{V_2}{2} + 0.625V_2$$

$$I_2 = -0.125V_2 + 0.625V_2 = 0.5V_2$$

⑤ Find the z-parameters of the RC ladder shown in the fig.



$$V_1(s) = \frac{1}{2} I_1(s) + 1 (I_1(s) - I_3(s)) \quad \text{--- (1)}$$

$$1 (I_3(s) - I_1(s)) + \frac{1}{2} I_3(s) + 1 (I_3(s) + I_2(s)) = V_2(s) \quad \text{--- (2)}$$

$$V_2(s) = (I_3(s) + I_2(s)) \cdot 1 - \textcircled{3}$$

rearranging eq ② to get I_3 in terms of I_1 & I_2

$$I_3(s) - I_1(s) + \frac{1}{2} I_3(s) + I_3(s) + I_2(s) = 0$$

$$I_3(s) \left[2 + \frac{1}{2} \right] = -I_2(s) + I_1(s)$$

$$I_3(s) \left[\frac{2s+1}{s} \right] = I_1(s) - I_2(s)$$

$$I_3(s) = \frac{s [I_1(s) - I_2(s)]}{2s+1} \quad \textcircled{4}$$

sub ④ in ① & ③

$$\text{eq ① } V_1(s) = \frac{1}{s} I_1(s) + 1(I_1(s) - I_3(s))$$

$$V_1(s) = \left(1 + \frac{1}{s}\right) I_1(s) - s \left[\frac{I_1(s) - I_2(s)}{2s+1} \right]$$

$$= \left[\left(\frac{s+1}{s}\right) - \frac{s}{(2s+1)} \right] I_1(s) + \frac{s}{2s+1} I_2(s)$$

$$\dots \dots \dots (2) I_1(s) + s I_2(s)$$

$$V_1(s) = \left[\frac{(2s+1)(s+1) - s^2}{s(2s+1)} \right] I_1(s) + \frac{s}{2s+1} I_2(s)$$

$$= \left[\frac{2s^2 + 2s + s + 1 - s^2}{s(2s+1)} \right] I_1(s) + \frac{s}{2s+1} I_2(s)$$

$$V_1(s) = \left[\frac{s^2 + 3s + 1}{s(2s+1)} \right] I_1(s) + \frac{s}{2s+1} I_2(s) \quad \text{--- (5)}$$

$Z_{11} \qquad Z_{12}$

eg (3) $V_2(s) = (I_3(s) + I_2(s)) R \times 1$

$$V_2(s) = \frac{s(I_1(s) - I_2(s))}{2s+1} + I_2(s)$$

$$V_2(s) = \frac{s I_1(s)}{2s+1} + \left[\frac{-s}{2s+1} + 1 \right] I_2(s)$$

$$V_2(s) = \frac{s I_1(s)}{2s+1} + \frac{s+1}{2s+1} I_2(s)$$

$Z_{21} \qquad Z_{22}$

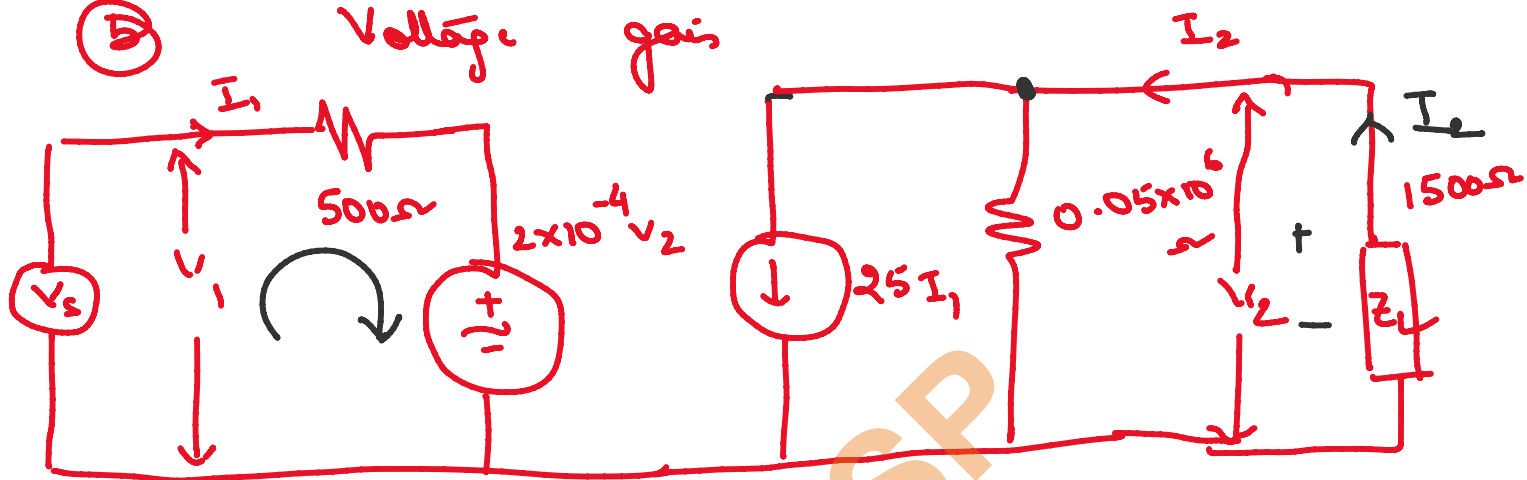
More problems on two port network parameters

16 January 2021 11:04

For a h-parameter eq. n/LS shown,

Ⓐ determine the current gain

Ⓑ Voltage gain



$$I_2 = \frac{25 I_1 \times 0.05 \times 10^6}{1500 + 0.05 \times 10^6}$$

$$A_I = \frac{I_2}{I_1} = \frac{25 \times 0.05 \times 10^6}{(1500 + 0.05 \times 10^6)} = 24.27 \quad \text{--- (1)}$$

$$V_1 = 500 I_1 + 2 \times 10^{-4} V_2 \quad \text{--- (2)} \quad I_2 = \frac{-V_2}{1500} \quad \text{--- (3)}$$

$$\text{KCL at output } I_2 = 25 I_1 + \frac{V_2}{0.05 \times 10^6} \quad \text{--- (4) } \checkmark$$

Ⓒ is Ⓓ

$$\frac{-V_2}{1500} = 25 I_1 + \frac{V_2}{0.05 \times 10^6} \quad \text{--- (5)}$$

$$\text{from eq (2)} \quad V_1 - 2 \times 10^{-4} V_2 = I_1 \quad \text{--- (6)}$$

from eq (2)
$$\frac{V_1 - 2 \times 10^{-4} V_2}{500} = I_1 \quad (6)$$

Sub (6) in (5)

$$-\frac{V_2}{1500} = 25 \times \left(\frac{V_1 - 2 \times 10^{-4} V_2}{500} \right) + \frac{V_2}{0.05 \times 10^6}$$

$$-\frac{V_2}{1500} = \frac{25V_1}{500} - \frac{25 \times 2 \times 10^{-4} V_2}{500} + \frac{V_2}{0.05 \times 10^6}$$

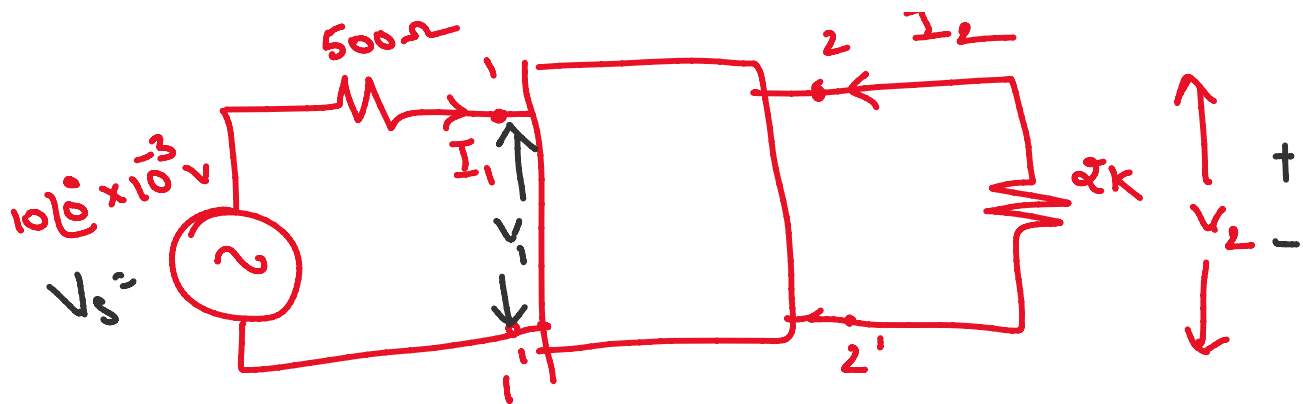
$$\frac{25V_1}{500} = V_2 \left[\frac{-1}{1500} + \frac{25 \times 2 \times 10^{-4}}{500} + \frac{1}{0.05 \times 10^6} \right]$$

$$\frac{V_1}{20} = V_2 \left[-6.77 \times 10^{-4} \right]$$

$$\frac{V_2}{V_1} = -73.89.$$

The hybrid parameters of a 2 port n/w shown is fig are $h_{11} = 1k$, $h_{12} = 0.03$, $h_{21} = 100$, $h_{22} = 50 \mu S$. Find V_2 and Z parameters of the n/w.





$$V_1 = h_{11} I_1 + h_{12} V_2 \quad - (1)$$

$$I_2 = h_{21} I_1 + h_{22} V_2 \quad - (2)$$

$$V_1 = 500 I_1 + 0.003 V_2 \quad - (1)$$

$$I_2 = 100 I_1 + 50 \mu V_2 \quad - (2)$$

$$-I_2 2000 = V_2 \quad - (3)$$

Sub (3) in (2)

$$I_2 = 100 I_1 - 50 \mu \times 2000 I_2$$

$$I_2 [1 + 50 \mu \times 2000] = 100 I_1$$

$$I_2 = \left(\frac{100}{1 + 50 \mu \times 2000} \right) I_1 \Rightarrow \frac{I_2}{I_1} = \frac{100}{1.1} \quad - (4)$$

Sub (4) in (1)

$$V_1 = 1 \text{ k} I_1 + 0.003 [-I_2 2000] \quad - (5)$$

$$V_s = 500 I_1 = V_1 \quad - (6)$$

eq (5) & (6) by eliminating V_1

$$V_s - 500 I_1 = 1k I_1 + 0.003 \left[-I_2 \cdot 2000 \right] \quad (7)$$

sub (4) in (7)

$$V_s = 500 I_1 + 1k I_1 + 0.003 \left[-\frac{100}{1.1} I_1 \cdot 2000 \right]$$

$$10 \times 10^{-3} = 954.54 I_1$$

$$I_1 = \frac{10 \times 10^{-3}}{954.54} = 10.5 \times 10^{-6} \text{ A}$$

$$V_1 = V_s - 500 I_1 = 10 \times 10^{-3} - 500 \times 10.5 \times 10^{-6} \\ = 4.75 \times 10^{-3} \text{ V}$$

$$V_2 = \frac{V_1 - h_{11} I_1}{h_{12}} \quad (\text{first } h \text{ parameter eq (5)}) \\ V_1 = h_{11} I_1 + h_{12} V_2$$

$$V_2 = \frac{4.75 \times 10^{-3} - 1k \times 10.5 \times 10^{-6}}{0.003} = -1.916 \text{ V}$$

$$Z_{11} = \frac{\Delta h}{h_{22}}$$

$$Z_{21} = \frac{-h_{21}}{h_{22}}$$

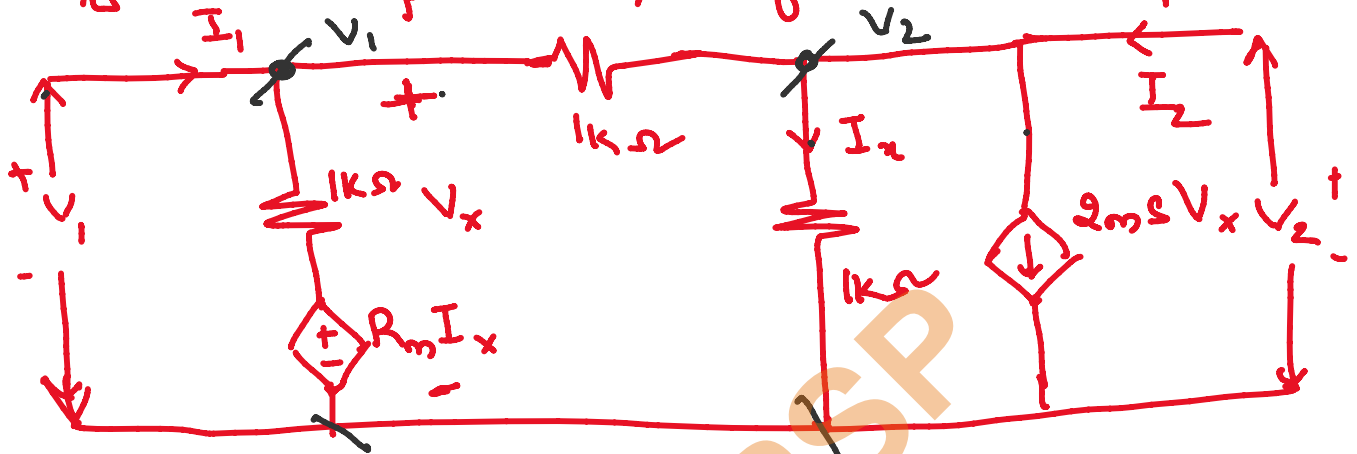
$$Z_{12} = \frac{h_{12}}{1}$$

$$Z_{22} = \frac{1}{h_{22}}$$

$$\epsilon_{12} = \frac{r_{12}}{h_{22}}$$

$$z_{22} = \frac{1}{h_{22}}$$

8) For the T_L shown below, find R_m if the T_L is reciprocal. Also find the h-parameters



$$V_1 = V_x - \textcircled{1}$$

$$I_x = \frac{V_2}{1k} - \textcircled{2}$$

Nodal at V_1

$$\frac{V_1 - R_m I_x}{1k} + \frac{V_1 - V_2}{1k} = I_1 - \textcircled{3}$$

Nodal at V_2

$$\frac{V_2 - V_1}{1k} + \frac{V_2}{1k} + 2mS V_x = I_2 - \textcircled{4}$$

sub $\textcircled{2}$ in $\textcircled{3}$ & $\textcircled{1}$ in $\textcircled{4}$

$$\frac{V_1 - R_m (V_2 \times 10^{-3})}{1k} + \frac{V_1 - V_2}{1k} = I_1$$

$$I_1 = \frac{2V_1}{1k} - \frac{V_2}{1k} [1 + R_m \times 10^{-3}]$$

$$I_1 = 2 \times 10^{-3} V_1 - 1 \times 10^{-3} V_2 [1 + R_m \times 10^{-3}] - \textcircled{5}$$

$$\frac{V_2 - V_1}{1k} + \frac{V_2}{1k} + 2mV_1 = I_2$$

$$I_2 = (2m - 1m)V_1 + V_2(1m + 1m)$$

$$I_2 = 1mV_1 + 2mV_2 \quad \text{--- (6)}$$

$$I_1 = 2mV_1 - (R_m \times 10^{-6} + 1m)V_2$$

$$I_2 = 1mV_1 + 2mV_2$$

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} 2m & -(R_m \times 10^{-6} + 1m) \\ 1m & 2m \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

Std. Y-parameters format.

Condition for Reciprocity in Y parameters

$$Y_{12} = Y_{21}$$

$$-R_m \times 10^{-6} - 1m = 1m$$

$$-R_m \times 10^{-6} = 2m$$

$$R_m = -\frac{2m}{10^{-6}} = \underline{\underline{-2k}}$$

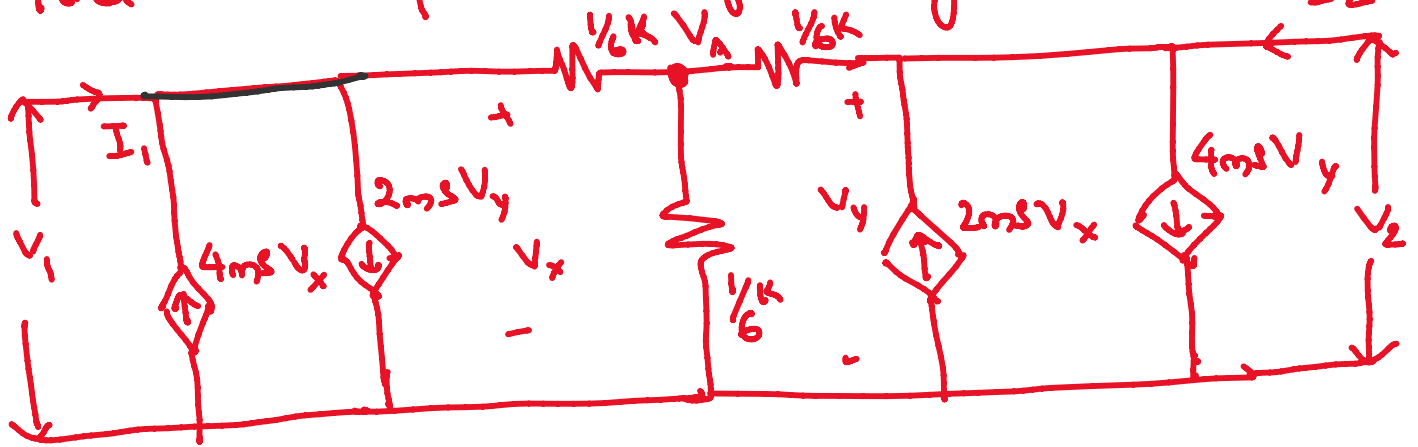


Z → h

h → Z

Z → Δ

⑨ Find the Y-parameters for the given circuit



$$V_x = V_1, \quad V_y = V_2$$

$$\text{At } V_1, \quad I_1 = -4\text{ms}V_x + 2\text{ms}V_y + \frac{V_1 - V_A}{\frac{1}{6}\text{k}}$$

$$I_1 = -4\text{ms}V_1 + 2\text{ms}V_2 + (V_1 - V_A)6\text{ms}$$

$$I_1 = 2\text{ms}V_1 + 2\text{ms}V_2 - 6\text{ms}V_A \quad \text{--- (1)}$$

$$\text{At } V_A, \quad \frac{V_A - V_1}{\frac{1}{6}\text{k}} + \frac{V_A}{\frac{1}{6}\text{k}} + \frac{V_A - V_2}{\frac{1}{6}\text{k}} = 0$$

$$-6\text{ms}V_1 - 6\text{ms}V_2 + 18\text{ms}V_A = 0$$

$$V_A = \frac{V_1 + V_2}{3} \quad \text{--- (2)}$$

$$\text{At } V_2, \quad I_2 = +4\text{ms}V_y + 2\text{ms}V_x + \frac{V_2 - V_A}{\frac{1}{6}\text{k}}$$

$$I_2 = -4\text{ms}V_1 + 2\text{ms}V_2 - 6\text{ms}(V_1 + V_2)$$

$$I_2 = -4ms V_2 + 2ms V_1 + 6ms (V_2 - V_A) \quad \widehat{6k}$$

$$I_2 = 2ms V_1 + 10ms V_2 + 6ms V_A - \quad (3)$$

$$\downarrow \quad V_A = \left(\frac{V_1 + V_2}{3} \right)$$

sub (2) in (3)

$$I_1 = 2ms V_1 + 2ms V_2 - 6ms V_A$$

$$= 2ms V_1 + 2ms V_2 - 6ms \left[\frac{V_1 + V_2}{3} \right]$$

$$I_1 = 0V_1 + 0V_2 - \quad (4)$$

$$I_2 = -2ms V_1 + 10ms V_2 + 6ms \left[\frac{V_1 + V_2}{3} \right]$$

$$= -2ms V_1 + 10ms V_2 + 2ms V_1 + 2ms V_2$$

$$I_2 = -4ms V_1 + 8ms V_2$$

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ -4ms & 8ms \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

$$\left| \begin{array}{l} I_2 \leftarrow \left(\frac{V_2 - V_A}{\frac{1}{6k}} \right) + 2ms V_x - 4ms V_y = 0 \end{array} \right.$$

$$\frac{1}{2} \left(\frac{v_2 - v_A}{\frac{1}{6}k} \right) + 2ms v_x - 4ms v_y = 0$$

NT by PSP

Network functions

09 January 2021 10:38

Driving pt Impedance

$$Z_{11}(s) = \frac{V_1(s)}{I_1(s)}$$

→ Roots of $V_1(s)$ are zeros
 → Roots of $I_1(s)$ are poles.

$$Z_{22}(s) = \frac{V_2(s)}{I_2(s)}$$

Short circuit

If $Z_{11}(s) = 0, V = 0$ (The zeros of $V(s)$ polynomial lead of zeros of $Z(s)$)

$Z_{11}(s) = \infty, I = 0$ (The zeros of $I(s)$ polynomial lead of poles of $Z(s)$)

Open circuit

$$G_{21}(s) = \frac{V_2(s)}{V_1(s)}$$

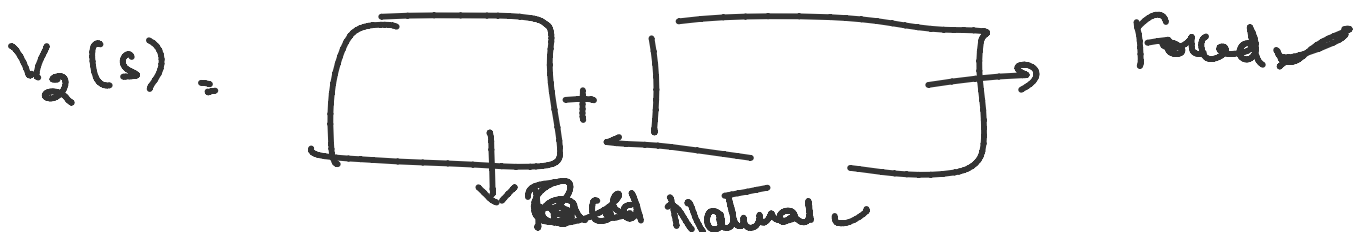
's' - domain

Time domain

n/w parameter

$$V_2(s) = \underbrace{G_{21}(s)}_{\text{I/p parameter}} V_1(s)$$

's' - domain



$$d_{21}(s) = \frac{I_2(s)}{I_1(s)}$$

$$I_2(s) = d_{21}(s) I_1(s)$$

N/P parameter

I/P parameter

$$R + sL$$

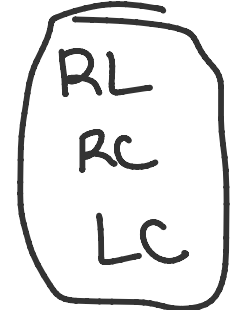
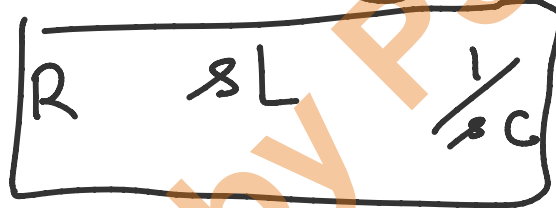
$$s(s^2 + 1)$$

$$s = \pm j1$$

$$R + \frac{1}{sC}$$

$$s(s + j1)$$

$$sL + \frac{1}{sL}$$



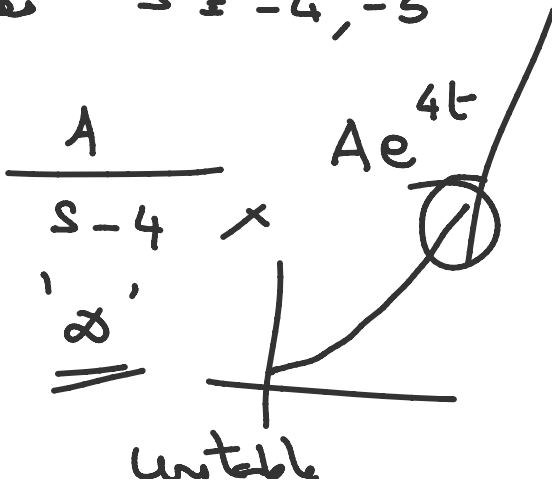
~~$$(s^2 + 2s + 5)$$~~

$$(s + 2)(s + 3)$$

$$(s + 4)(s + 5)$$

Zeros $s = -2, -3$

poles $s = -4, -5$



$$\frac{A}{s + 4} + \frac{B}{s + 5}$$

$$Ae^{-4t}$$

$$P = -4$$

Stable

$$e^{pt}$$

At $t = \infty$, $y(t) = 0$

Pole (v)

unstable

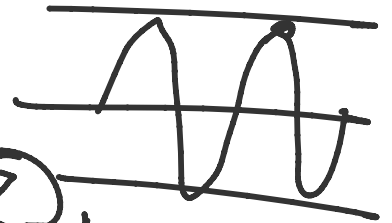
π (LVC)

$\frac{j}{s} = 0$

$$\frac{A}{(s^2 + a^2)^2}$$

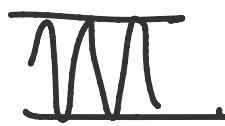
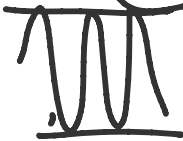
$t \sin \omega t$

$t \cos \omega t$



$\sin \omega t \rightarrow$ magnitude

$$\frac{A}{(s^2 + a^2)(s^2 + b^2)}$$



Z_{12}

Resistor = $R \cdot \Omega$ (Z_{res})

$$(j\omega L) = \Omega$$

$$(\Omega)$$

Inductance = $L s^2 \times (1)$

$$\frac{1}{j\omega C} (\Omega)$$

Capacitance = $\frac{1}{C s} (1)$

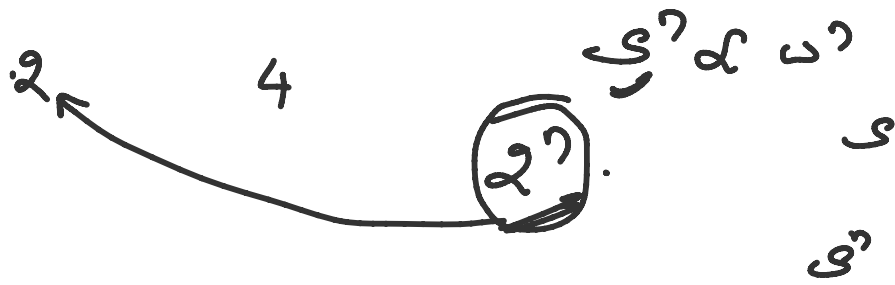
$R, Ls, \frac{1}{Cs}$ Valid Resistance eq. is s domain

$$s = \sigma + j\omega$$

$$s \propto \omega$$

$$s^2 \propto \omega^2$$

$$s^0 \propto \omega^0$$



$$Z(s) = \left(\lim_{s \rightarrow \infty} \frac{a_0 s^n + \dots}{b_0 s^m + \dots} \right) = \lim_{s \rightarrow \infty} \frac{a_0 s^n}{b_0 s^m}$$

$$= \lim_{s \rightarrow \infty} \frac{a_0 s^{n-m}}{b_0}$$

$$n-m=0$$

$$n-m=1$$

$$n-m=-1$$



Highest order must diff by

0 or 1



$$\frac{I_2}{V_1}$$

$$R_3(I_1 - I_2)$$

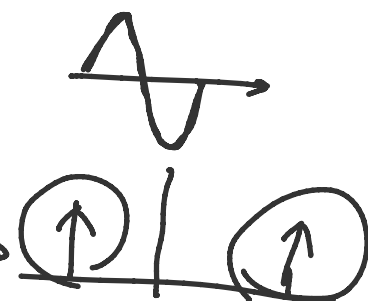
1) Frequency Domain study ?

F.T, F.S etc \rightarrow Freq. domain.

Time domain — To visual is easy. Signal change $\text{d}t \rightarrow \text{time}$

For analysis — Freq. domain ?

FM — MHz

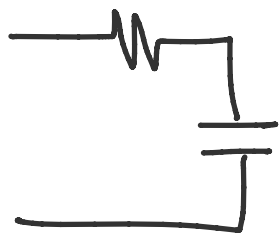


Freq. domain



RC

$$\frac{1}{1 + e^{-t/\tau}}$$

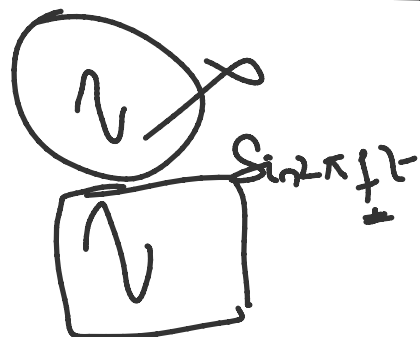


LPF ?

Widens \rightarrow

Narrow \rightarrow

Tran
Recu.



$\sin 2\pi ft$



HPF

Freq. Domain - ① F.T - Fourier Transform

{ freq. components?
 how will they be affected when passed
 thro' a particular system?
 ↳ HP? B?
 ↳ LP?

① FT

$$F(\omega) = \frac{1}{T} \int_{t_1}^{t_2} e^{-j\omega t} f(t) dt$$

$$e^{-j\omega t} = \cos t - j \sin t$$

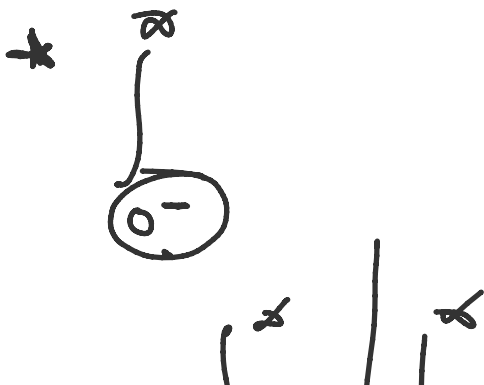
$f(t)$ - Signal is time domain

$$\int_0^{\infty} f(t) dt = \text{Finite Value}$$

$$\int_0^{\infty} \underline{u(t)} dt = t \Big|_0^{\infty} = \infty \quad \int \mathcal{L} t dt = \frac{\mathcal{L} t^2}{2} = \infty$$

$$\int e^{\mathcal{L} t} = \frac{e^{\mathcal{L} t}}{\mathcal{L}} = \infty$$

②



Time domain

$$\frac{v_c(0^-)}{X}$$

$$\underbrace{i_L(0^-)}_X$$

$$\int_{-\infty}^{\infty} \frac{dx}{x} \quad \Bigg| \quad \int_{-\infty}^{\infty} \frac{dx}{x - 0}$$

Laplace Transform :-

$$L[f(t)] = \int_{-\infty}^{\infty} \left[e^{-j\omega t} \cdot \boxed{f(t)} \cdot e^{-\sigma t} \right] dt$$

*
 $e^{-\sigma t} \rightarrow e^{-\sigma} = 0$
 $0 \times \frac{1}{0}$

① $L[f(t)] = \int_{-\infty}^{\infty} e^{-(\sigma + j\omega)t} f(t) dt$

Causal Systems $= \int_{-\infty}^{\infty} e^{-st} f(t) dt$

$s = \sigma + j\omega$

② $L[f(t)] = \int_{\boxed{0^-}}^{\infty} e^{-st} f(t) dt$ (Laplace Transform Covers the Initial Conditions)

③ * Absolute Integrable * $\int_{0^-}^{\infty} e^{-st} f(t) dt + \int_0^{\infty} e^{-st} f(t) dt$
 Initial conditions

Initial Value Theorem :-

* $f(0^-) = \lim_{s \rightarrow \infty} s F(s)$ * Initial Value of $\underline{f(s)}$ at $\underline{t=0}$

$$* \quad f(0^-) = \lim_{s \rightarrow \infty} sF(s) \quad * \quad \underline{\underline{K_{in} = 0}}$$

Final Value Theorem

$$* \quad f(\infty) = \lim_{s \rightarrow 0} sF(s) \quad *$$

Steady state Response is TD

NT by PSP

Resistor

$$v_R(t) = i_R(t) \times R$$

G - Conductance

$$i_R(t) = \frac{v_R(t)}{R} = G v_R(t)$$

Laplace Domain

$$V_R(s) = I_R(s) \cdot R \quad \text{or} \quad I_R(s) = G V_R(s)$$

$$R = \frac{V_R(s)}{I_R(s)} \quad \text{or} \quad G = \frac{I_R(s)}{V_R(s)}$$

Inductance

$$v_L(t) = L \frac{di_L(t)}{dt}$$

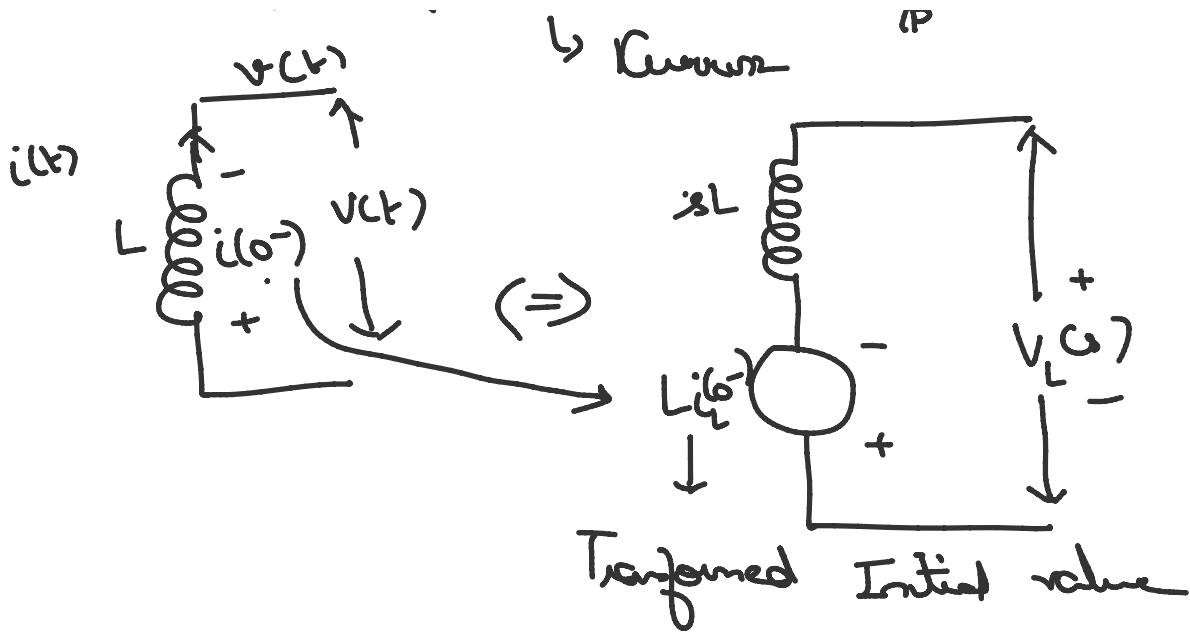
$$\Rightarrow \text{or} \quad i_L(t) = \frac{1}{L} \int_{-\infty}^t v_L(t) dt = \frac{1}{L} \int_{0^-}^t v_L(t) dt$$

$$* I_L(s) = \frac{V_L(s)}{Ls} + \left[\frac{i_L(0^-)}{s} \right] \rightarrow \text{Initial value} \quad \text{--- (1)}$$

$$\Rightarrow V_L(s) = sL I(s) - L i_L(0^-)$$

$$\Rightarrow * V(s) = L [s I(s) - i_L(0^-)] \quad \text{--- (2)}$$

$V_L(s)$ & $I(s)$ - ^L The $\frac{v}{i}$ that is used.
 $\frac{v(t)}{i(t)}$ \hookrightarrow Resistor



Capacitor

$$v_c(t) = \frac{1}{C} \int_{-\infty}^t i dt$$

$$i(t) = C \frac{dv_c(t)}{dt}$$

$$V_c(s) = \frac{1}{C} \left[\frac{I(s)}{s} + \frac{q(0^-)}{s} \right]$$

$$v = \frac{q}{C}$$

$$q = vC$$

$$= \frac{I(s)}{Cs} + \left[\frac{q(0^-)}{Cs} \right] = \frac{I(s)}{Cs} + \frac{V_0}{s}$$

$$i = \frac{dq}{dt}$$

$$\int i = q$$

$$\checkmark V_c(s) = \frac{I(s)}{Cs} + \frac{V_0}{s} \quad \text{--- (1)}$$

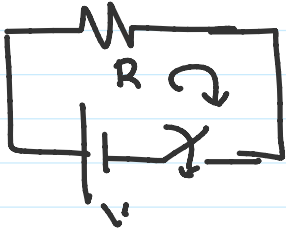
$$\frac{I(s)}{Cs} = V_c(s) - \frac{V_0}{s}$$

$$\checkmark I(s) = Cs V_c(s) - \cancel{C V_0} \quad \text{--- (2)}$$

Transformed
Initial
Voltage

DC excitation

03 October 2020 11:06



$$V = iR$$

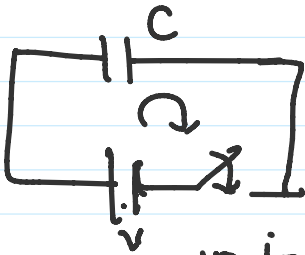
$$V(s) = I(s)R$$

$$I(s) = \frac{V(s)}{R} = \frac{V}{sR} \quad sL$$

$$V(s) = \mathcal{L}[v] = \frac{V}{s}$$

$$i = C \frac{dv}{dt}$$

$$\frac{dv}{dt} = \frac{1}{s} \cdot \mathcal{L}(v)$$

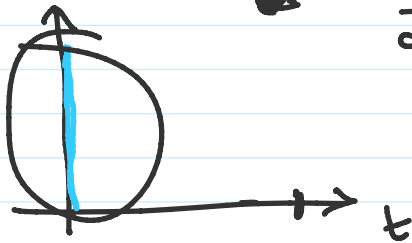
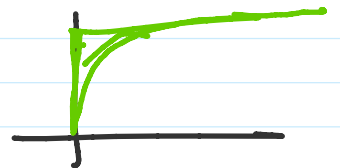


$$= I(s) \frac{1}{Cs} \cdot V(s) = \frac{V/s}{Cs}$$

$$i = C \frac{dv}{dt} \Rightarrow I(s) = VC$$

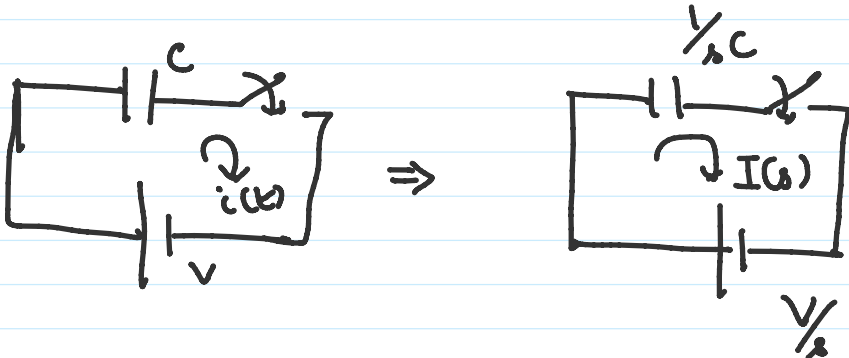
$$I(s) = VC$$

$$i(t) = VC \delta(t)$$



$$i(s) = i(t) = \int_{-\infty}^{\infty} \delta(t) e^{-st} dt = \int_{-\infty}^{\infty} VC \delta(t) e^{-st} dt = VC$$

$$i(\infty) = \lim_{s \rightarrow 0} s i(s) = \lim_{s \rightarrow 0} s VC = 0$$



$$i = C \frac{dv}{dt}$$

$$= C \cdot s \cdot \mathcal{L}[v(t)]$$

$$\left. \begin{aligned} v(t) &= V \\ v(s) &= \frac{V}{s} \\ C &= \frac{1}{j\omega C} \\ &= \frac{1}{sR} \end{aligned} \right\}$$

$$= C \cdot s \cdot L [v(t)] \quad // \quad = \frac{1}{sC}$$

$$I(s) = C s \cdot \frac{V}{s} = CV$$

$$I(s) = \frac{V/s}{1/sC} = \underline{VC}$$

$$\Rightarrow i(t) = VC \delta(t)$$

Initial Value Theorem

$$i(0^+) = \lim_{s \rightarrow \infty} s I(s) = \lim_{s \rightarrow \infty} s VC = \infty$$

Final Value Theorem

$$\left[\begin{array}{l} i \frac{dv}{dt} = 0 \text{ when } v_c = V \\ \underline{= 0} \end{array} \right]$$

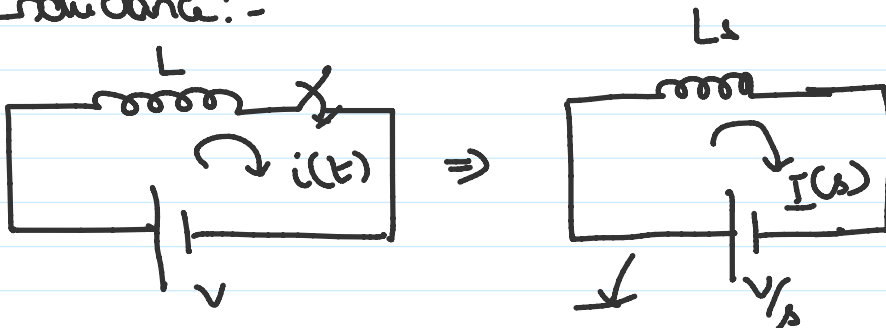
$$i(\infty) = \lim_{s \rightarrow 0} s I(s) = \lim_{s \rightarrow 0} s VC = 0$$

$$\mathcal{L}^{-1}[i] = \delta(t)$$

' ∞ '

If no voltage is present is C_{op} at $t=0^-$ at $t=0^+$ $v_c(t) = 0$ 'SC'

Inductance:-



$$I(s) = \frac{V/s}{Ls} = \frac{V}{L s^2} \quad \textcircled{1}$$

$$i(t) = \frac{1}{L} \int v dt \Rightarrow I(s) = L \left[\frac{1}{L} \int v dt \right]$$

$$= \frac{1}{L} L \left[\int v dt \right] = \frac{1}{L} \cdot \frac{1}{s} L(v(t))$$

$$\boxed{L \int f(t) = \frac{1}{s} L[f(s)]} \quad \checkmark \quad I(s) = \frac{1}{Ls} \cdot \frac{V}{s} = \frac{V}{Ls^2} \quad (2)$$

Time domain $i(t) = L^{-1} \left[\frac{V}{Ls^2} \right] = \frac{V}{L} t \quad (3)$
Rep. of current

$$L[t] = \frac{1}{s^2}$$

\checkmark $i(0^-)$ through L is 0. $i(0^+)$ is also 0.

Initial Value Theorem

$$i(0^+) = \lim_{s \rightarrow \infty} s I(s) = \lim_{s \rightarrow \infty} s \cdot \frac{V}{Ls^2} = 0.$$

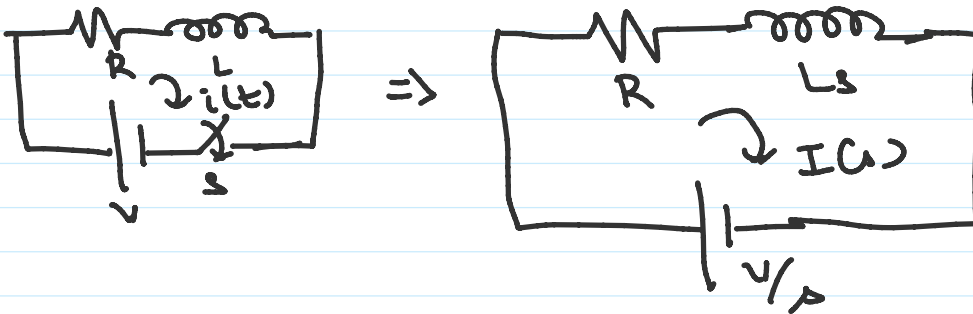
Final value theorem

$$i(\infty) = \lim_{s \rightarrow 0} s I(s) = \lim_{s \rightarrow 0} s \cdot \frac{V}{Ls^2} = \frac{V}{L} = \infty$$

Because L acts as SC at $t = \infty$

$$\left[v = L \frac{di}{dt} = 0 \right].$$

RL Circuit :-



$$I(s) = \frac{V/s}{R + Ls} = \frac{V}{s(R + Ls)} = \frac{V}{sL \left[s + \frac{R}{L} \right]}$$

$$I(s) = \frac{V/L}{s \left(s + \frac{R}{L} \right)}$$

$$I(s) = \frac{A}{s} + \frac{B}{\left(s + \frac{R}{L} \right)} \quad \text{--- (1)}$$

$$A = \lim_{s \rightarrow 0} s \cdot \frac{V/L}{s \left(s + \frac{R}{L} \right)} = \frac{V}{R} \quad \text{--- (2)}$$

$$B = \lim_{s \rightarrow -\frac{R}{L}} \left(s + \frac{R}{L} \right) \frac{V/L}{s \left(s + \frac{R}{L} \right)} = \frac{V/L}{-\frac{R}{L}} = -\frac{V}{R} \quad \text{--- (3)}$$

sub (2) & (3) in (1)

$$I(s) = \frac{V}{R} - \frac{V}{R \left(s + \frac{R}{L} \right)}$$

$$i(t) = \frac{V}{R} - \frac{V}{R} e^{-\frac{R}{L}t}$$

$$\mathcal{L}^{-1} \left[\frac{1}{s} \right] = 1$$

$$\mathcal{L}^{-1} \left[\frac{1}{s+a} \right] = e^{-at}$$

$$i(t) = \frac{V}{R} - \frac{V}{R} e^{-\frac{t}{\tau}}$$

$$i(t) = \frac{V}{R} [1 - e^{-\frac{R}{L}t}] = \frac{V}{R} [1 - e^{-\frac{t}{\tau}}]$$

$\tau = \frac{L}{R}$

From Initial Value Theorem

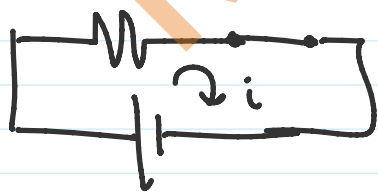
$$i(0^+) = \lim_{s \rightarrow \infty} s \cdot \frac{V/L}{s(s + R/L)} = \frac{V/L}{\infty} = 0.$$

[Because of inductor $i(0^-) = 0$, $i(0^+) = 0$.]

From final value theorem

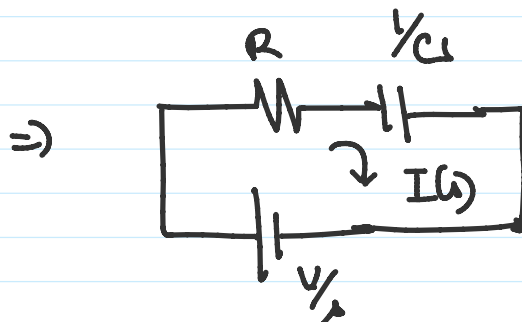
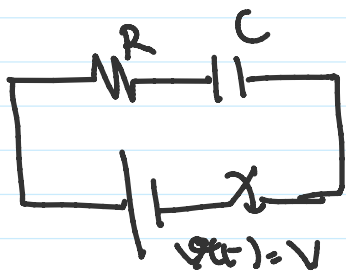
$$i(\infty) = \lim_{s \rightarrow 0} s \cdot \frac{V/L}{s(s + R/L)} = \frac{V}{R}$$

[At $t = \infty$, L acts as a SC, so the voltage V appears across $R \Rightarrow i(\infty) = \frac{V}{R}$]



$$i = \frac{V}{R}$$

RC Circuit:-



$$I(\infty) = \frac{V}{R} = \frac{V}{R}$$

$$I(s) = \frac{V/A}{R + 1/Cs} = \frac{V/A}{\frac{RCs + 1}{Cs}}$$

$$I(s) = \frac{V/A}{R} \cdot \frac{Cs}{RCs + 1} = \frac{VC}{RCs + 1} = \frac{VC}{RC \left[s + \frac{1}{RC} \right]}$$

$$I(s) = \frac{V/R}{\left[s + \frac{1}{RC} \right]} \quad \mathcal{L}^{-1} \left[\frac{A}{s+a} \right] = A e^{-at}$$

$$i(t) = \frac{V}{R} e^{-t/RC} = \frac{V}{R} e^{-t/\tau} = \frac{V}{R} e^{-t/\tau}$$

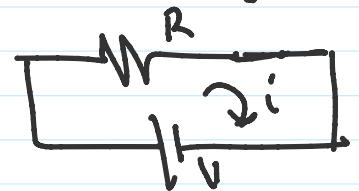
$$I(s) = \frac{V/R}{s + 1/RC}$$

$$i(0^+) = \lim_{s \rightarrow \infty} s I(s) = \lim_{s \rightarrow \infty} s \cdot \frac{V/R}{s + 1/RC} = \lim_{s \rightarrow \infty} \frac{s \left[\frac{V}{R} \right]}{s \left[1 + \frac{1}{RCs} \right]}$$

$$= \frac{V/R}{1+0} = V/R$$

At $t=0^-$, $v_c(0^-)=0$ so $t=0^+$ also $v_c(0^+)=0$.
 so the whole voltage appears across R .

$$\Rightarrow i = \frac{V}{R}$$



$$i(\infty) = \lim_{s \rightarrow 0} s I(s) = \lim_{s \rightarrow 0} s \cdot \frac{V/R}{s + 1/RC} = 0$$

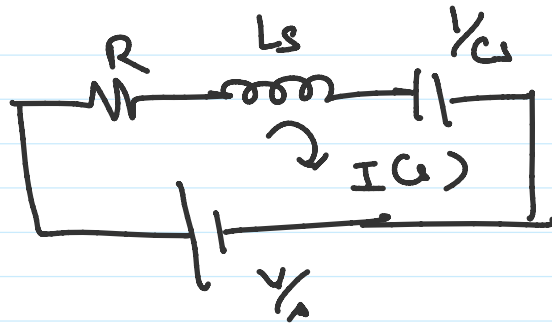
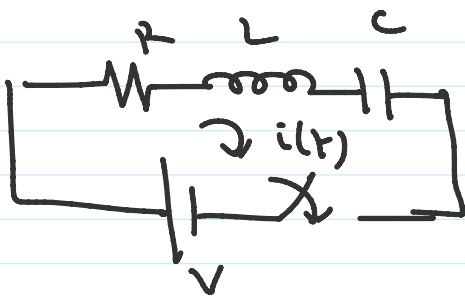
$$i(\infty) = \lim_{s \rightarrow 0} s I(s) = \lim_{s \rightarrow 0} s \cdot \frac{V/R}{s + \frac{1}{RC}} = 0$$

At $t = \infty$, Capacitor behaves like OC. not allowing any current
 $i = C \frac{dv}{dt} \Rightarrow i = 0.$

NIT by PSP

DC excitation for RLC Circuit

08 October 2020 11:02



$$I(s) = \frac{\frac{V}{s}}{R + Ls + \frac{1}{Cs}} = \frac{V/s}{RCs + (Ls^2 + 1)}$$

$$= \frac{V}{s} \cdot \frac{C}{1 + LCs^2 + RCs} = \frac{VC}{LC \left[s^2 + \frac{RC}{L}s + \frac{1}{LC} \right]}$$

$$I(s) = \frac{\frac{V}{L}}{\left(s^2 + \frac{R}{L}s + \frac{1}{LC} \right)}$$

$$s = \frac{-\frac{R}{L} \pm \sqrt{\left(\frac{R}{L}\right)^2 - \frac{4}{LC}}}{2}$$

$$I(s) = \frac{\frac{V}{L}}{\left[s + \frac{R}{2L} - \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}} \right] \left[s + \frac{R}{2L} + \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}} \right]}$$

$$\int \frac{V}{L} \frac{R}{2L} = a \quad \& \quad b = \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

$$\Rightarrow I(s) = \frac{\frac{V}{L}}{(s+a-b)(s+a+b)}$$

$$I(s) = \frac{V/2bL}{(s+a-b)} - \frac{V/2bL}{(s+a+b)}$$

$$\checkmark i(t) = \frac{V}{2bL} \left[e^{-(a-b)t} - e^{-(a+b)t} \right] \quad \text{--- (1)}$$

$$I_f \quad \left(\frac{R}{2L} \right)^2 > \frac{1}{LC}, \quad b \text{ is real}$$

$$I_f \quad \left(\frac{R}{2L} \right)^2 = \frac{1}{LC}, \quad b \text{ is zero}$$

$$I_f \quad \left(\frac{R}{2L} \right)^2 < \frac{1}{LC}, \quad b \text{ is imaginary.}$$

Case 1:- b is real, positive

$$i(t) = \frac{V}{2bL} \left[e^{-(a-b)t} - e^{-(a+b)t} \right]$$

Case 2:- b is zero

$$\Rightarrow i(t) = \frac{V}{2bL} \left[e^{-at} - e^{-at} \right] \text{ an indeterminate}$$

Diff $i(t)$ wrt t .

$$\rightarrow i(t) = \frac{V}{L} t e^{-at}$$

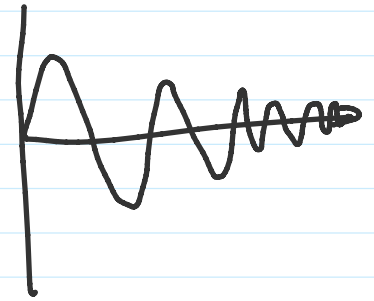
Case 3:- I_f b is imaginary

$$i(t) = \frac{V}{L} \left(e^{-at + jbt} - e^{-at - jbt} \right)$$

$$i(t) = \frac{V}{2bL} \left(e^{-at} e^{jbt} - e^{-at} e^{-jbt} \right)$$

$$= \frac{V}{2bL} e^{-at} \left(e^{jbt} - e^{-jbt} \right)$$

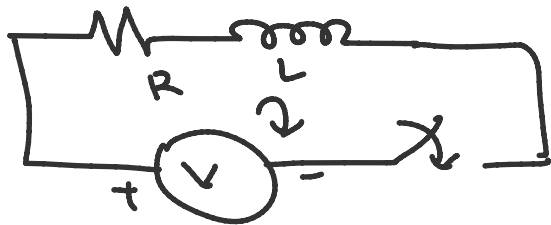
$$= \frac{V}{2bL} e^{-at} \cdot 2 \cdot \sin bt$$



NIT by PSP

Sin excitation for RL circuits

08 October 2020 11:13



$$v(t) = V_m \sin(\omega t + \phi)$$

$$I(\omega) = \frac{V(\omega)}{Z(\omega)} = \frac{V_m}{R + j\omega L} \left[L[\sin \omega t] \cos \phi + L[\cos \omega t] \sin \phi \right]$$

$$\bar{I}(\omega) = \frac{V_m}{R + j\omega L} \left[\frac{\omega}{s^2 + \omega^2} \cos \phi + \frac{s}{s^2 + \omega^2} \sin \phi \right]$$

Let $\frac{R}{L} = a$.

$$I(\omega) = \frac{V_m}{L(s + \frac{R}{L})} \left[\frac{\omega \cos \phi}{(s^2 + \omega^2)} + \frac{s \sin \phi}{s^2 + \omega^2} \right]$$

$$= \frac{V_m/L}{(s+a)} \left[\frac{\omega \cos \phi}{(s^2 + \omega^2)} + \frac{s \sin \phi}{(s^2 + \omega^2)} \right]$$

$$I(\omega) = \frac{V_m}{L} \left[\frac{\omega \cos \phi}{(s+a)(s^2 + \omega^2)} + \frac{s \sin \phi}{(s+a)(s^2 + \omega^2)} \right]$$

$$\frac{1}{(s+a)(s^2 + \omega^2)} = \frac{1}{(a^2 + \omega^2)} \left(\frac{1}{(s+a)} + \frac{a}{s^2 + \omega^2} - \frac{s}{s^2 + \omega^2} \right)$$

$$\frac{1}{(s+a)(s^2+\omega^2)} = \frac{1}{(a^2+\omega^2)} \left[\frac{(s+a)}{s^2+\omega^2} - \frac{1}{s+a} \right]$$

$$\frac{s}{(s+a)(s^2+\omega^2)} = \frac{1}{(a^2+\omega^2)} \left[\frac{as}{s^2+\omega^2} + \frac{\omega^2}{s^2+\omega^2} - \frac{a}{s+a} \right]$$

$$i(t) = \frac{V_m}{(a^2+\omega^2) \cdot L} \left[\omega \cos \phi \left(e^{-at} + \frac{a}{\omega} \sin \omega t - \cos \omega t \right) + \sin \phi \left[a \cos \omega t + \omega \sin \omega t - a e^{-at} \right] \right]$$

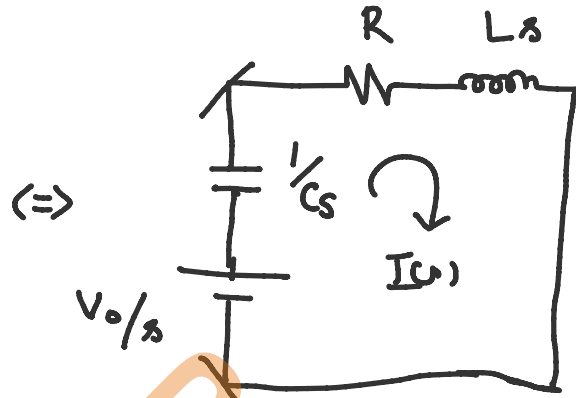
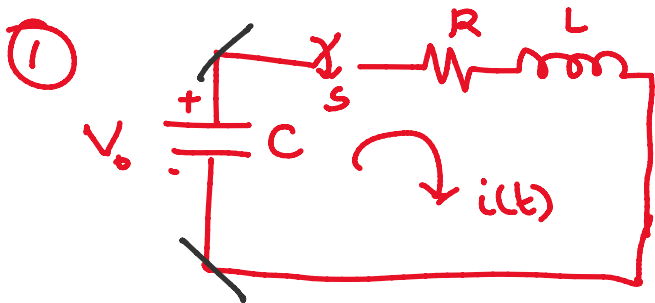
NT by PSP

Problems on Laplace

15 December 2020 13:22

$$V(s) = sLI(s) - Li(0^-) \quad \text{--- (1)}$$

$$V(s) = \frac{I(s)}{sC} + \frac{V_c(0^-)}{s} \quad \text{--- (2)}$$



$$RI(s) + LsI(s) + \frac{1}{Cs}I(s) = \frac{V_0}{s}$$

$$\left(R + Ls + \frac{1}{Cs}\right) I(s) = \frac{V_0}{s}$$

$$I(s) = \frac{\frac{V_0}{s}}{R + Ls + \frac{1}{Cs}} = \frac{V_0}{L \left(s^2 + \frac{R}{L}s + \frac{1}{LC}\right)}$$

$$= \frac{V_0}{L} \cdot \frac{1}{(s+a)^2 + b^2} = \frac{V_0}{L} \cdot \frac{1}{(s^2 + 2as + a^2 + b^2)}$$

$$a = \frac{R}{2L}, \quad b = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$$

$$I(s) = \frac{V_0 \cdot b}{bL (s+a)^2 + b^2} = \frac{V_0}{bL} \cdot \frac{b}{(s+a)^2 + b^2}$$

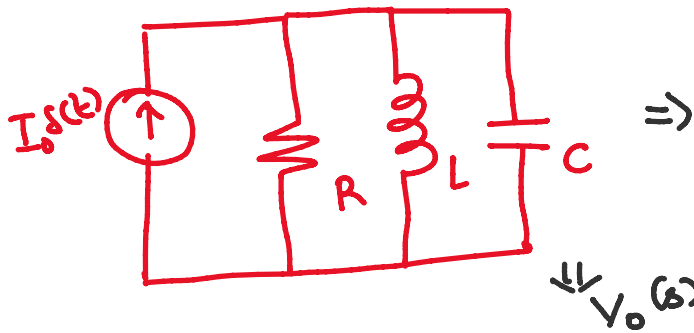
$$i(t) = \frac{V_0}{bL} \cdot e^{-at} \sin bt$$

②

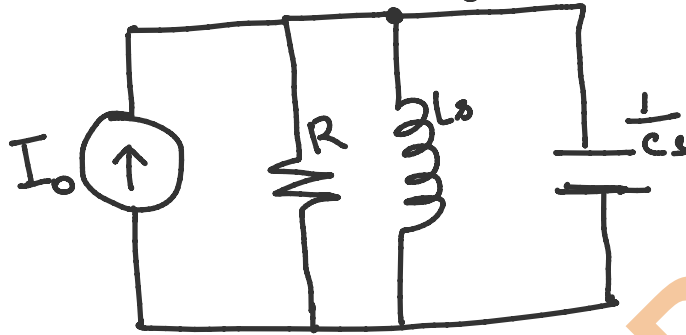


All initial conditions
 $t = 0^-$ $t = 0^-$ $t = 0^-$ $t = 0^-$

②



All initial conditions taken to be zero
the ckt can be drawn in Laplace domain as follows



$$\frac{V_0(s)}{R} + \frac{V_0(s)}{Ls} + \frac{V_0(s)}{1/Cs} = I_0$$

$$\Rightarrow V_0(s) \left[\frac{1}{R} + \frac{1}{Ls} + Cs \right] = I_0$$

$$\Rightarrow V_0(s) \left[\frac{Ls + R + RLCs^2}{RLs} \right] = I_0$$

$$\Rightarrow V_0(s) = \frac{I_0 \cdot RLs}{RLCs^2 + Ls + R}$$

Divide the N_x & D_x with RLC

$$V_0(s) = \frac{I_0/c s}{s^2 + \frac{1}{RC}s + \frac{1}{LC}}$$

$$= \frac{I_0 s}{C}$$

$$= \frac{\frac{I_0}{C} s}{s^2 + 2s \cdot \frac{1}{2RC} + \left(\frac{1}{2RC}\right)^2 + \frac{1}{LC} - \left(\frac{1}{2RC}\right)^2}$$

$$= \frac{\frac{I_0}{C} s}{\left(s + \frac{1}{2RC}\right)^2 + \left(\sqrt{\frac{1}{LC} - \frac{1}{4R^2C^2}}\right)^2}$$

$$V_0(s) = \frac{\frac{I_0}{C} s}{(s+a)^2 + b^2} \quad \text{where } a = \frac{1}{2RC}$$

$$b = \sqrt{\frac{1}{LC} - \frac{1}{4R^2C^2}}$$

$$V_0(s) = \frac{\frac{I_0}{C} s}{(s+a)^2 + b^2} = \frac{I_0}{C} \cdot \frac{s}{(s+a)^2 + b^2}$$

$$= \frac{I_0}{C} \cdot \left(\frac{(s+a) - a}{(s+a)^2 + b^2} \right)$$

$$= \frac{I_0}{C} \left[\frac{s+a}{(s+a)^2 + b^2} \right] - \frac{I_0}{C} \cdot \frac{a}{b} \cdot \frac{b}{(s+a)^2 + b^2}$$

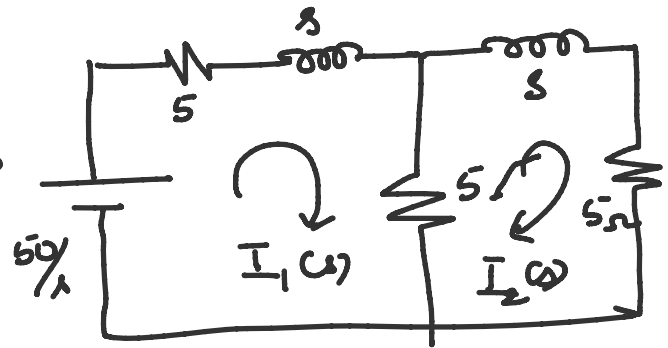
$$V_0(t) = \frac{I_0}{C} \left[e^{-at} \cos bt \right] - \frac{I_0}{C} \cdot \frac{a}{b} \cdot e^{-at} \sin bt$$

$$V_o(t) = \frac{I_0}{c} \left[e^{-at} \cos bt - \frac{a}{b} e^{-at} \sin bt \right]$$

③



(\Leftrightarrow)



$$\frac{50}{s} = 5 I_1(\omega) + 8 I_1(\omega) + 5 (I_1(\omega) - I_2(\omega)) \quad \text{--- (1)}$$

$$5 (I_2(\omega) - I_1(\omega)) + 8 I_2(\omega) + 5 I_2(\omega) = 0 \quad \text{--- (2)}$$

$$(10 + 8) I_1(\omega) - 5 I_2(\omega) = 50/s$$

$$-5 I_1(\omega) + (10 + 8) I_2(\omega) = 0$$

$$\begin{bmatrix} 10+8 & -5 \\ -5 & 10+8 \end{bmatrix} \begin{bmatrix} I_1(\omega) \\ I_2(\omega) \end{bmatrix} = \begin{bmatrix} 50/s \\ 0 \end{bmatrix}$$

$$I_1(\omega) = \frac{\begin{vmatrix} 50/s & -5 \\ 0 & 10+8 \end{vmatrix}}{\begin{vmatrix} 10+8 & -5 \\ -5 & 10+8 \end{vmatrix}} = \frac{\frac{50}{s} (10+8)}{(10+8)^2 - 25}$$

$$I_1(s) = \frac{50(s+10)}{s[s^2+20s+100-25]} = \frac{50(s+10)}{s[s^2+20s+75]}$$

$$= \frac{50(s+10)}{s[s^2+15s+5s+75]} = \frac{50(s+10)}{s[s(s+5)+5(s+5)]}$$

$$I_1(s) = \frac{50(s+10)}{s(s+5)(s+15)} = \frac{A}{s} + \frac{B}{(s+5)} + \frac{C}{(s+15)}$$

$$A = \lim_{s \rightarrow 0} \frac{\cancel{s} \cdot 50(s+10)}{s \cancel{(s+5)}(s+15)} = \frac{500}{5 \times 15} = \frac{20}{3}$$

$$B = \lim_{s \rightarrow -5} \frac{\cancel{(s+5)} 50(s+10)}{s \cancel{(s+5)}(s+15)} = \frac{50(-5+10)}{(-5)(-5+15)} = \frac{-50 \times 5}{5 \times 10} = -5$$

$$C = \lim_{s \rightarrow -15} \frac{\cancel{(s+15)} 50(s+10)}{s \cancel{(s+15)}(s+5)} = \frac{50(-15+10)}{-15 \times (-15+5)} = \frac{50 \times -5}{-15 \times (-10)}$$

$$= -\frac{5}{3}$$

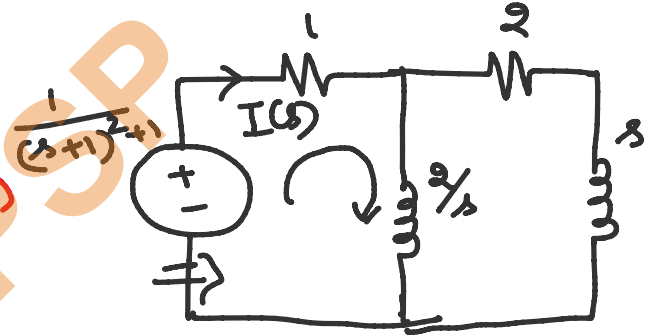
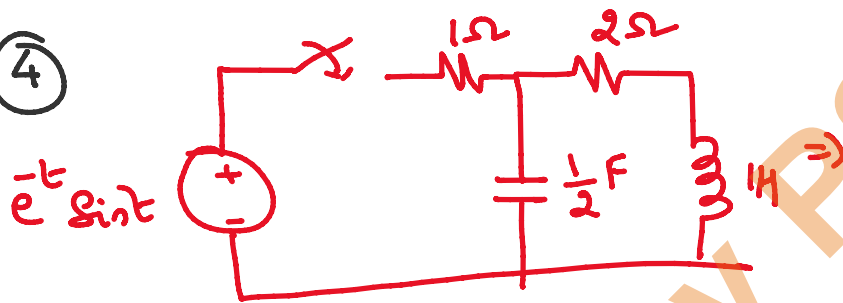
$$I_1(s) = \frac{20}{3s} - \frac{5}{s+5} - \frac{5}{3(s+15)}$$

$$i_1(t) = 2\frac{5}{3}u(t) - 5e^{-5t} - \frac{5}{3}e^{-15t}$$

$$I_2(s) = \frac{10}{3s} - \frac{5}{s+5} + \frac{1.67}{s+15}$$

$$i_2(t) = 10\frac{1}{3}u(t) - 5e^{-5t} + 1.67e^{-15t}$$

④



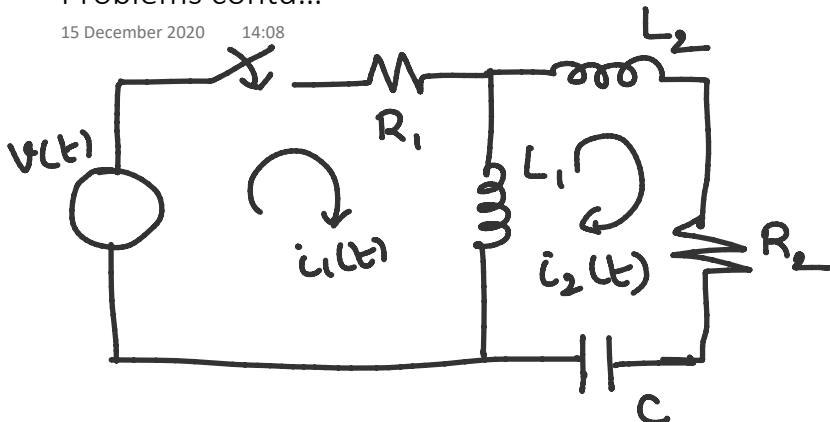
$$L[e^{-t} \sin t] = \frac{b}{(s+a)^2 + b^2} = \frac{1}{(s+1)^2 + 1} \quad C = \frac{1}{2}$$

$$= \frac{2}{s} \in C_s = \frac{1}{\frac{1}{2}s}$$

$$Z_{eq} =$$

Problems contd...

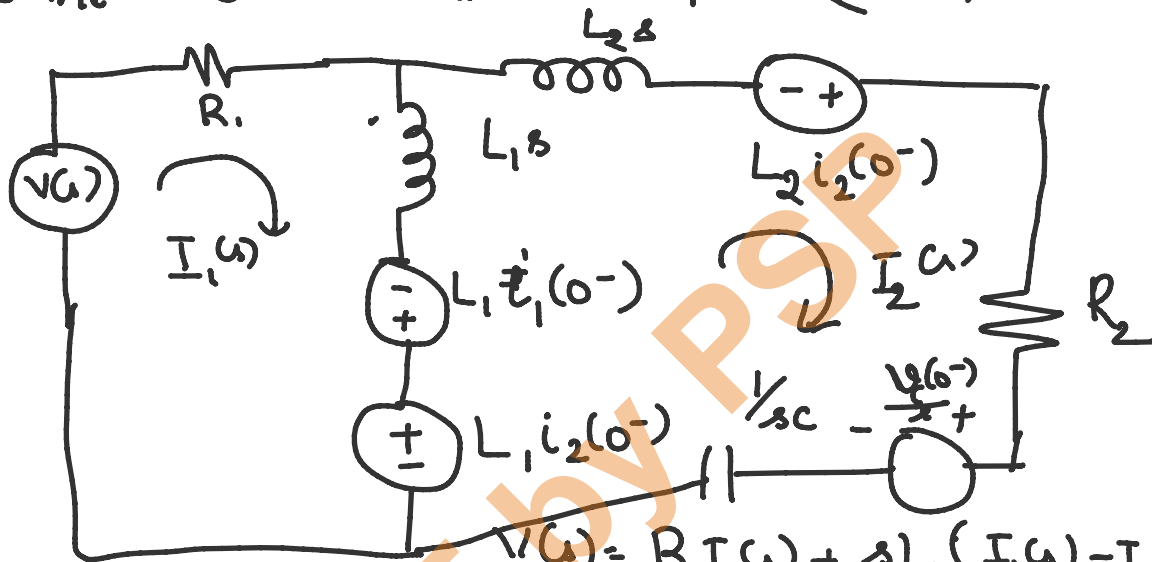
15 December 2020 14:08



$$V(s) = \frac{sL_1 I(s) - L_1 i(0^-)}{sC} + \frac{V_c(0^-)}{s}$$

$$V(s) = \frac{I(s)}{sC} + \frac{V_c(0^-)}{s}$$

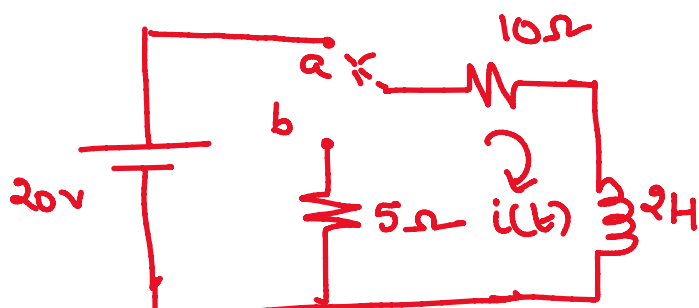
So the current thro' L_1 is $(i_1 - i_2)$

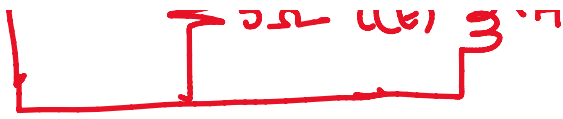


$$V(s) = R I_1(s) + sL_1 (I_1(s) - I_2(s)) - L_1 i_1(0^-) + L_1 i_2(0^-) \quad \text{--- (1)}$$

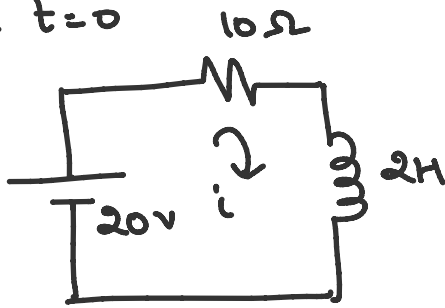
$$- L_1 i_2(0^-) + L_1 i_1(0^-) + L_1 s (I_2(s) - I_1(s)) + L_2 s I_2(s)$$

$$- L_2 i_2(0^-) + R_2 I_2(s) + \frac{V_c(0^-)}{s} + \frac{1}{sC} I_2(s) = 0 \quad \text{--- (2)}$$





Before $t=0$

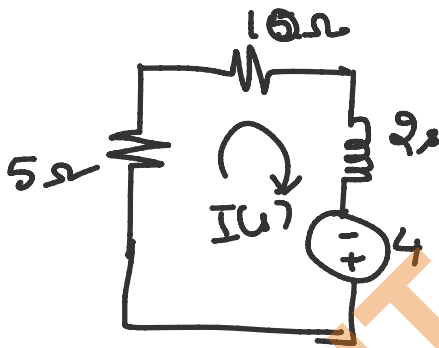


Steady state by the time it is $t=0$.
At s.s. $L \Rightarrow \text{sc}$ (acts as a)

$$i = \frac{20}{10} = 2 \text{ Amps}$$

The current thro' inductor across by $t=0$ is 2Amps.

At $t=0$, the switch is changed to position B



$$V(t) = L \frac{dI(t)}{dt} - Li(0^-)$$

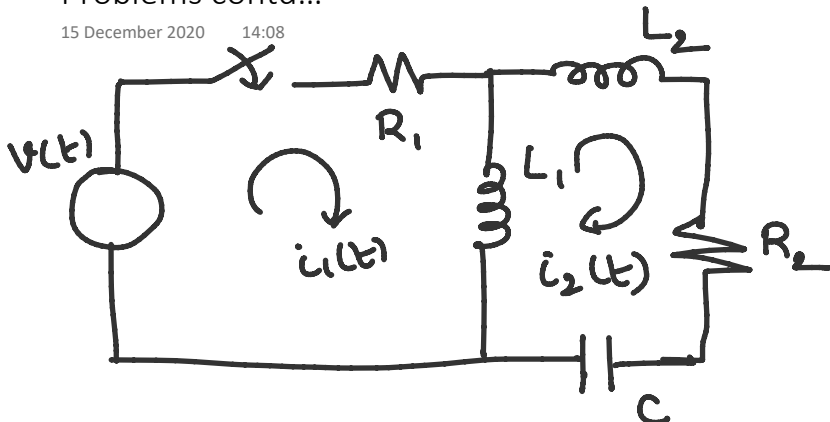
$$= 2 \frac{dI(t)}{dt} - 2 \times 2$$

$$4 = (15 + 2s) I(t) \quad I(t) = \frac{4}{2s + 15} = \frac{2}{s + 7.5}$$

$$i(t) = 2e^{-7.5t} \text{ Amps}$$

Problems contd...

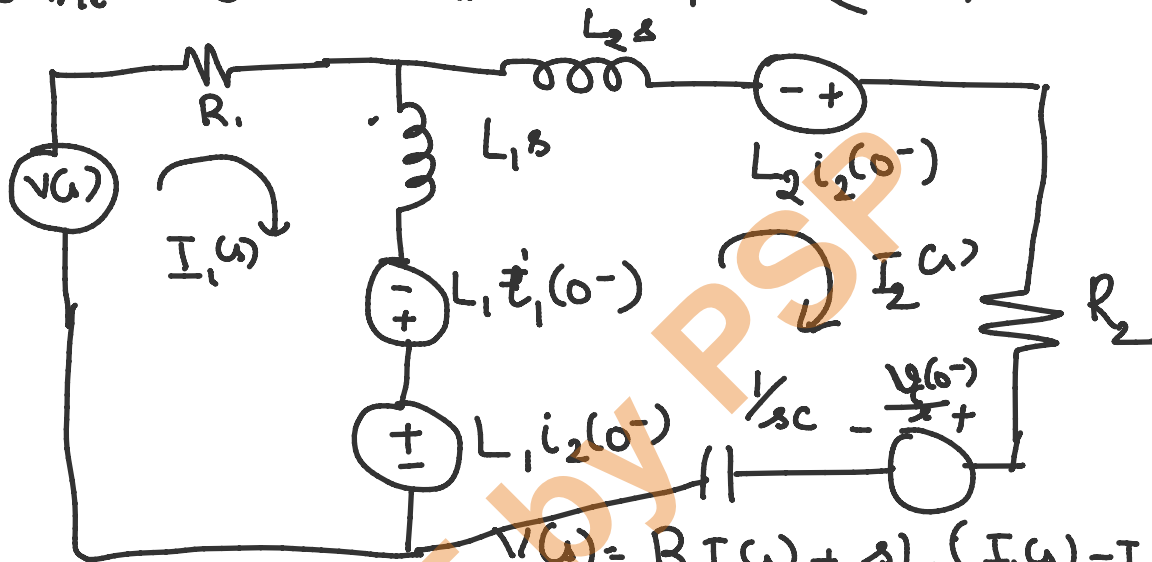
15 December 2020 14:08



$$V(s) = \frac{sLI(s) - Li(0^-)}{sC} + \frac{V_c(0^-)}{s}$$

$$V(s) = \frac{I(s)}{sC} + \frac{V_c(0^-)}{s}$$

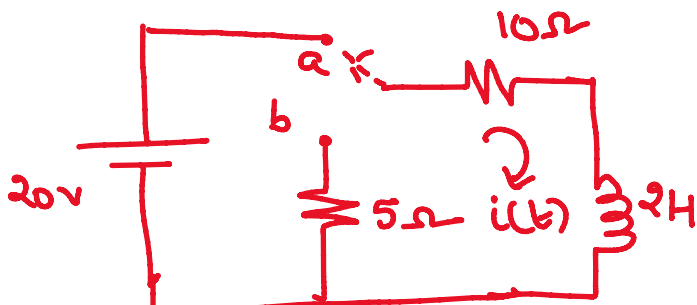
So the current thro' L_1 is $(i_1 - i_2)$

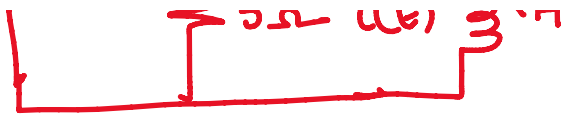


$$V(s) = R I_1(s) + sL_1(I_1(s) - I_2(s)) - L_1 i_1(0^-) + L_1 i_2(0^-) \quad \text{--- (1)}$$

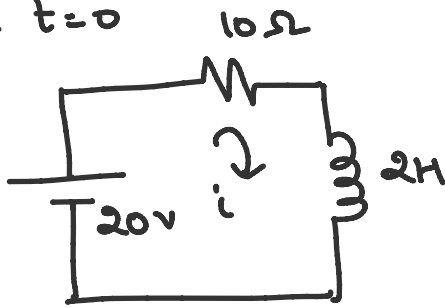
$$- L_1 i_2(0^-) + L_1 i_1(0^-) + L_1 s(I_2(s) - I_1(s)) + L_2 s I_2(s)$$

$$- L_2 i_2(0^-) + R_2 I_2(s) + \frac{V_c(0^-)}{s} + \frac{1}{sC} I_2(s) = 0 \quad \text{--- (2)}$$





Before $t=0$

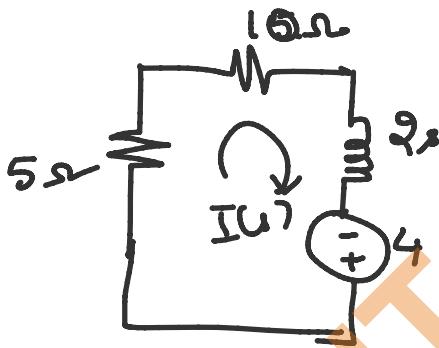


Steady state by the time it is $t=0$.
At s.s. $L \Rightarrow \text{sc}$ (acts as a)

$$i = \frac{20}{10} = 2 \text{ Amps}$$

The current thro' inductor across by $t=0$ is 2Amps.

At $t=0$, the switch is changed to position B



$$V(t) = L \frac{dI(t)}{dt} - Li(0^-)$$

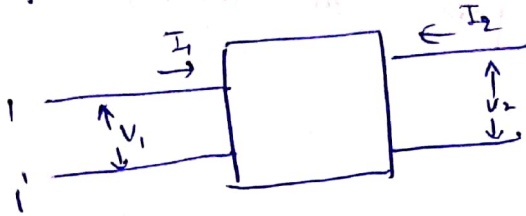
$$= 2 \frac{dI(t)}{dt} - 2 \times 2$$

$$4 = (15 + 2s) I(t) \quad I(t) = \frac{4}{2s + 15} = \frac{2}{s + 7.5}$$

$$i(t) = 2e^{-7.5t} \text{ Amps}$$

Network Function

Network functions give the relation between the transform of the excitation to the transform of the response.



The driving point impedance at port 1-1' is the ratio of the transform voltage at port 1-1' to the transform current at the same port

$$Z_{11}(s) = \frac{V_1(s)}{I_1(s)}$$

Similarly at port 2-2' is

$$Z_{22}(s) = \frac{V_2(s)}{I_2(s)}$$

Also the driving point admittances can be defined as

$$Y_{11}(s) = \frac{I_1(s)}{V_1(s)}$$

$$Y_{22}(s) = \frac{I_2(s)}{V_2(s)}$$

Two Port Network

The four other network functions are called transfer functions.

These functions give the relation between voltage or current at one port to the voltage or current at another port as shown.

Voltage Transfer Ratio :

$$G_{21}(s) = \frac{V_2(s)}{V_1(s)}, \quad G_{12}(s) = \frac{V_1(s)}{V_2(s)}$$

Current Transfer Ratio

$$d_{12}(s) = \frac{I_1(s)}{I_2(s)}, \quad d_{21}(s) = \frac{I_2(s)}{I_1(s)}$$

Transfer Impedance

$$Z_{21}(s) = \frac{V_2(s)}{I_1(s)}, \quad Z_{12}(s) = \frac{V_1(s)}{I_2(s)}$$

Transfer Admittance

$$Y_{12}(s) = \frac{I_1(s)}{V_2(s)}, \quad Y_{21}(s) = \frac{I_2(s)}{V_1(s)}$$

Pole And Zero

Let $N(s)$, the network function be written as

$$N(s) = \frac{P(s)}{Q(s)} = \frac{a_0 s^n + a_1 s^{n-1} + a_2 s^{n-2} + \dots + a_{n-1} s + a_n}{b_0 s^m + b_1 s^{m-1} + b_2 s^{m-2} + \dots + b_{m-1} s + b_m}$$

where a_0, a_1, \dots, a_n and b_0, b_1, \dots, b_m are the coefficients of the polynomials $P(s)$ and $Q(s)$, they are real and positive for a passive network.

If the numerator and denominator of $N(s)$ are factorized, the network function can be written as

$$N(s) = \frac{P(s)}{Q(s)} = \frac{a_0 (s-z_1)(s-z_2) \dots (s-z_n)}{b_0 (s-p_1)(s-p_2) \dots (s-p_m)}$$

where z_1, z_2, \dots, z_n are n roots of $P(s) = 0$
 p_1, p_2, \dots, p_m are m roots of $Q(s) = 0$

$\frac{a_0}{b_0}$ - H-scale factor.

z_1, z_2, \dots, z_n are called zeros of the polynomial $N(s)$ and are denoted by o .

p_1, p_2, \dots, p_m are called poles of the polynomial $N(s)$ and are denoted by x .

The function $N(s)$ becomes zero when s is equal to anyone of the zeros. $N(s)$ becomes infinite when s is equal to anyone of the poles. A network function is completely defined by poles and zeros.

If poles and zeros are not repeated, then the function is said to be simple poles or simple zeros.

If poles and zeros are repeated, then the function is said to be having multiple poles & multiple zeros.

When $n > m$, then $(n-m)$ zeros are at $s = \infty$
for $m > n$, $(m-n)$ poles are at $s = \infty$.

The network function is said to be stable when the real parts of the zeros or poles are negative. Else, the poles and zeros must lie in the left half of s -plane.

Necessary Conditions for Driving Point Function

The restrictions on pole and zero locations in the driving point function with common factors cancelled are listed below.

1. The coefficients in the polynomials $P(s)$ & $Q(s)$ of the network function $N(s) = \frac{P(s)}{Q(s)}$ must be real and positive.

2. Complex or imaginary pole and zeros must occur in conjugate pairs.

3. a. The real part of all poles and zeros must be zero, or negative

b. If the real part is zero, then the pole and zeros must be ~~zero~~ simple.

4. The polynomials $P(s)$ and $Q(s)$ may not have any missing terms between the highest and the lowest degrees, unless all even or all odd terms are missing.

5. The degree of $P(s)$ and $Q(s)$ may differ by zero, or one only.

6. The lowest degree in $P(s)$ and $Q(s)$ may differ by the most one.

Necessary Conditions for Transfer Functions

The restrictions on pole and zero location in transfer functions with common factors in $P(s)$ & $Q(s)$ cancelled are listed

1. a. The coefficients in the polynomials $P(s)$ & $Q(s)$ must be real.
of $N(s) = P(s)/Q(s)$

b. The coefficients in $Q(s)$ must be positive, but some of the coefficients in $P(s)$ may be negative.

2. Complex ~~and~~ or imaginary poles and zeros must occur in conjugate pairs.
3. The real parts of poles must be $-ve$, or zero. If the real part is zero, then the pole must be simple.
4. The polynomial $Q(s)$ may not have any missing terms between the highest and the lowest degree, unless all even or all odd terms are missing.
5. The polynomial $P(s)$ may have missing terms between the lowest and the highest degree.
6. The degree of $P(s)$ may be as small as zero, indep. independent of the degree of $Q(s)$.
7. a. For voltage and current transfer ratios, the maximum degree of $P(s)$ must equal the degree of $Q(s)$.
- b. For transfer impedance and transfer admittance, the max. degree of $P(s)$ must equal the degree of $Q(s)$ plus one.

Significance of Pole and Zero

Pole and zero are critical frequencies. At poles, the network function become infinite, while at pole zero, the network function become zero.

At other complex frequencies, the network function has a finite non-zero value.

Pole and zero provide useful information is network function. Consider the following cases.

(a) Driving Point Impedance

$$Z(s) = \frac{V(s)}{I(s)}$$

A pole of $Z(s)$ implies zero current for a finite voltage which means an open circuit. A zero of $Z(s)$ implies no voltage for a finite current or a short circuit.

(b) Driving point Admittance

$$Y(s) = \frac{I(s)}{V(s)}$$

A pole of $Y(s)$ implies zero voltage for a finite current which means a short circuit. A zero of $Y(s)$ implies zero current for a finite value of voltage which give an open circuit.

© Voltage Transfer Ratio

$$G_{21}(s) = \frac{V_2(s)}{V_1(s)} \Rightarrow V_2(s) = G_{21}(s) V_1(s)$$

To obtain output voltage, we require the product of input and transfer function.

By using partial fractions, we can obtain a pole of $G_{21}(s)$ or $V_1(s)$

$$G_{21}(s) V_1(s) = \sum_{i=1}^n \frac{A}{s-a_i} + \sum_{j=1}^m \frac{B}{s-a_j}$$

where n and m are the no. of poles of $G_{21}(s)$ and $V_1(s)$ respectively.

The frequencies a_i from the natural complex function frequencies corresponding to free oscillation and depend on the network function $G_{21}(s)$, where a_j the frequencies a_j constitute the complex frequencies corresponding to forced oscillation and depend on the driving force $V_1(s)$.

From the above discussion, it can be observed that the poles determine the time variation of the response whereas the zeros determine the magnitude response.

(d) other network functions

Significance of poles and zeros in other transfer functions is the same as discussed above.

In each of the cases, poles determine the time domain behaviour and zeros determine the magnitude of each of the terms of the response.

Properties of Driving Point Functions

C4S1

a. The driving point function is a ratio of polynomial in s . Polynomials are obtained from the transform impedances of the elements and their combinations.

$$\left. \begin{aligned} P(s) &= a_0 s^n + a_1 s^{n-1} + \dots + a_{n-1} s + a_n \\ Q(s) &= b_0 s^m + b_1 s^{m-1} + \dots + b_{m-1} s + b_m \end{aligned} \right\} \text{--- (1)}$$

are the numerator & denominator polynomials respectively.

$$P(s) = (s - z_1)(s - z_2) \dots (s - z_n)$$

$$Q(s) = (s - p_1)(s - p_2) \dots (s - p_m)$$

$$\Rightarrow N(s) = \frac{P(s)}{Q(s)}$$

z_1, z_2, \dots, z_n are called zeros of $N(s)$. p_1, p_2, \dots, p_m are called poles of $N(s)$ [$N(p_1) = N(p_2) = \dots = N(p_m) = \infty$]

b) i. $N(s)$ is a driving point impedance @ $z(s)$

$$N(s) = z(s) = \frac{V(s)}{I(s)}$$

A zero of $N(s)$ is a zero of $V(s)$ & a pole of $N(s)$ is a zero of $I(s)$. poles of $z(s)$ are then freq. corresponding to open circuit

ii. $N(s) = Y(s) = \frac{I(s)}{V(s)}$, A zero of $Y(s)$ is a zero of $I(s)$ & pole of $Y(s)$ is a zero of $V(s)$.

c. Since all the elements in the circuit are real positive quantities the coefficients $a_0, a_1, a_2, \dots, a_n$ & b_0, b_1, \dots, b_m are real and positive. Therefore, any zeros and poles, if complex, must occur in conjugate pairs.

d. The real parts of all zeros and poles must be negative or zero. Using partial fractions, we know that this gives rise to a term of a form $\frac{A}{s-p}$ where inverse will be e^{pt} . The real part of e^{pt} tends to zero as t tends to infinity if p is a -ve quantity.

e. Poles & zeros lying on jw axis must be simple. If not the time response will be of the form $t^k e^{j\omega t}$ which tends to infinity as t tends to infinity. So the fn becomes unstable.

f. The degree of $P(s)$ and $Q(s)$ may differ by zero or one only.

At very high freq. the term $a_0 s^n$ dominates over the other terms in the numerator & the term $b_0 s^m$ dominates over other terms in the denominator.

$$\lim_{s \rightarrow \infty} N(s) = \lim_{s \rightarrow \infty} \frac{a_0 s^{n-m}}{b_0}$$

Consider R, L, C & M

If $n=m$, the function $R = \frac{a_0}{b_0}$

$n=m+1$, the function is L.

$m=n+1$, the function is like $\frac{1}{s}$ (all for

admittance)

g. The lowest degree in $P(s)$ & $Q(s)$ may differ by zero or one only.

As $s \rightarrow 0$, the higher power of s tends to 0 faster than s .

So $N(s) = \frac{a_{n-1}s + a_n}{b_{m-1}s + b_m}$

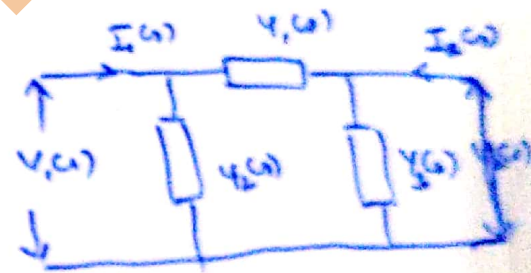
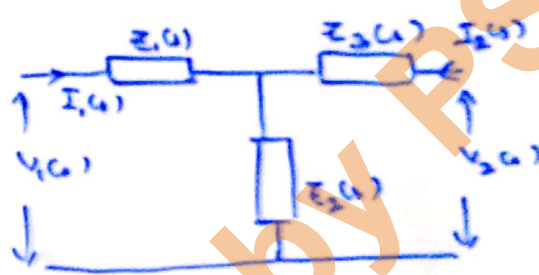
$N(s)$ is of the form k_1, k_2s or $\frac{k_3}{s}$. Hence $P(s)$ & $Q(s)$ can differ at most in one degree.

h. $P(s)$ and $Q(s)$ cannot have missing terms unless all even or all odd degree terms are absent.

An RL, RC and RLC may have form $(as+b)$, $(a+bs)$ and (as^2+bs+c) . If it is a combination of L & C then it is of the form (as^2+b) . If something of this form is multiplied by s , then the resulting function contains only odd powers of s .

Properties of Transfer Functions

- The transfer function is a ratio of polynomials in s .
- For stability, the poles must be real & -ve or complex conjugate pairs.
- There are no restrictions on the zeros of the transfer function, $P(s)$ can have missing terms. Also the coefficient of powers of s in $P(s)$ can be -ve.
- For $G(s)$ and $Z(s)$, the degree of the numerator polynomial $P(s)$ is less than or equal to the degree of $Q(s)$.



$$G(s) = \frac{V_2(s)}{V_1(s)} = \frac{Z_2(s)}{Z_1(s) + Z_2(s)} \quad \text{--- (1)}$$

$$Z(s) = \frac{I_2(s)}{I_1(s)} = \frac{Y_2(s)}{Y_1(s) + Y_2(s)} \quad \text{--- (2)}$$

$Z_1(s), Z_2(s)$ & $Z_L(s)$, $Y_1(s), Y_2(s)$ & $Y_L(s)$ can be thought of as the driving point functions of some one port. They have to satisfy the properties of driving point admittance functions.

$$Z_1(s) = K \frac{(s+d_1)(s+d_2) \dots (s+d_{n_1})}{(s+\beta_1)(s+\beta_2) \dots (s+\beta_{m_1})}$$

$$Z_2(s) = K_2 \frac{(s+r_1)(s+r_2) \dots (s+r_{n_2})}{(s+\delta_1)(s+\delta_2) \dots (s+\delta_{m_2})}$$

Then the degree of $P(s) = n_1 + m_2$ & degree of $Q(s) = n_2 + m_1$, which even is greater

If $n_1 + m_2 > n_2 + m_1$, the degree of $P(s)$ equals the degree of $Q(s)$.

If $n_1 + m_2 < n_2 + m_1$, degree of $Q(s) = n_2 + m_1$ and degree of $P(s)$ is less than degree of $Q(s)$.

Similarly, assuming $Y_1(s)$ & $Y_2(s)$ as ratios of polynomials and substituting these expressions in $d(s)$, it can be shown that the degree of the numerator of $d(s)$ is less than or equal to the degree of denominator.